# Phase transitions in self-gravitating systems and bacterial populations with a screened attractive potential

P. H. Chavanis and L. Delfini

Laboratoire de Physique Théorique (IRSAMC), CNRS and UPS, Université de Toulouse, F-31062 Toulouse, France (Received 13 January 2010; published 6 May 2010)

We consider a system of particles interacting via a screened Newtonian potential and study phase transitions between homogeneous and inhomogeneous states in the microcanonical and canonical ensembles. For small screenings, the interaction is long range. Like for other systems with long-range interactions, we obtain a great diversity of microcanonical and canonical phase transitions depending on the dimension of space and on the importance of the screening length. We also consider a system of particles in Newtonian interaction (without screening) in the presence of a "neutralizing background." By a proper interpretation of the parameters, our study describes (i) self-gravitating systems in a cosmological setting, and (ii) chemotaxis of bacterial populations in the original Keller-Segel model.

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# I. INTRODUCTION

Many biological species like bacteria, amoebae, endothelial cells, or even ants interact through the phenomenon of chemotaxis [1]. These organisms secrete a chemical substance (like a pheromone) that has an attractive (or sometimes repulsive) action on the organisms themselves. This phenomenon is responsible for the self-organization and morphogenesis of many biological species. It has also been proposed as a leading mechanism for the formation of blood vessels during embriogenesis [2]. On a theoretical point of view, chemotaxis can be described by the Keller-Segel (KS) [3] model or its generalizations [4]. The Keller-Segel model consists in a drift-diffusion equation for the evolution of the density of bacteria  $\rho(\mathbf{r},t)$  coupled to a reaction-diffusion equation for the evolution of the secreted chemical  $c(\mathbf{r}, t)$ . In certain approximations, the reaction-diffusion equation is replaced by a Poisson equation. In that case, the KS [3] model becomes isomorphic to the Smoluchowski-Poisson (SP) system [5] describing self-gravitating Brownian particles (see, e.g., [6] for a description of this analogy). The KS model and SP system have been studied thoroughly in applied mathematics (see references in [7]) and in theoretical physics (see references in [5]).

However, the original KS model [3] also allows for the possibility that the chemical suffers a degradation process which has the effect of reducing the range of the interaction. In that case, the Poisson equation is replaced by a screened Poisson equation [8]. In the gravitational analogy, this amounts to replacing the gravitational potential by a screened gravitational potential, i.e., an attractive Yukawa potential. In that case, there exists interesting phase transitions between spatially homogeneous and spatially inhomogeneous equilibrium distributions. This is a physical motivation to consider the thermodynamics of N-body systems interacting via an attractive Yukawa potential [9]. This will be called the screened Newtonian model. We shall also consider a related model where the interaction is not screened but the Poisson equation is modified so as to allow for the existence of spatially homogeneous distributions at equilibrium. This will be called the modified Newtonian model. In that model, the source of the potential is the deviation between the actual density  $\rho(\mathbf{r},t)$  and the average density  $\bar{\rho}$ . This is similar to the effect of a "neutralizing background" in plasma physics [10]. This model can be derived from the Keller-Segel model in the limit of vanishing degradation of the chemical [11]. It also appears in cosmology, due to the expansion of the universe, when we work in the comoving frame [12]. It is therefore interesting to consider this form of interaction at a general level and study the corresponding phase transitions. We shall also compare them with the ones obtained within the ordinary Newtonian model involving the usual Poisson equation [13–31] (see a review in [32]).

The paper is organized as follows. In Sec. II, we discuss several kinetic models taken from astrophysics, plasma physics, and biology for which our study applies. We consider either isolated systems described by the microcanonical ensemble (fixed energy E) or dissipative systems described by the canonical ensemble (fixed temperature T). We characterize their equilibrium states in the mean-field approximation: in the microcanonical ensemble (MCE), they maximize the entropy at fixed mass and energy, and in the canonical ensemble (CE), they minimize the free energy at fixed mass. In Sec. III, we specifically consider the case of a Newtonian interaction with a neutralizing background. We study phase transitions between homogeneous and inhomogeneous states depending on the dimension of space. In d=1, the system presents canonical and microcanonical second-order phase transitions. In d=2, the system presents an isothermal collapse in CE (zeroth-order phase transition) and a first-order phase transition in MCE. In d=3, the system presents an isothermal collapse in CE and a gravothermal catastrophe in MCE (zeroth-order phase transitions). In Sec. IV, we perform a similar study for the attractive Yukawa potential with screening length  $k_{0-}^{-1}$ . In d=1, there exists a canonical tricritical point  $(k_0)_c R = \sqrt{2}\pi \approx 4.44$  and a microcanonical tricritical point  $(k_0)_m R \simeq 11.8$ , where R is the system size. If  $k_0$  $\langle (k_0) \rangle_c$ , the system presents canonical and microcanonical second-order phase transitions. In that case, the ensembles are equivalent. If  $(k_0)_c < k_0 < (k_0)_m$ , the system presents a canonical first-order phase transition and a microcanonical second-order phase transition. In that case, there exists a region of negative specific heats in MCE and the ensembles are inequivalent. If  $k_0 > (k_0)_m$ , the system presents canonical and microcanonical first-order phase transitions. In d=2 and d=3, the phase transitions are similar to those reported for the modified Newtonian model. In Sec. V, we study the dynamical stability of the homogeneous phase and analytically determine the critical point  $(E_c^*, T_c^*)$  that marks the onset of instability of the homogeneous branch and the starting point of the bifurcated inhomogeneous branch. Direct numerical simulations associated with these phase transitions will be reported in a forthcoming paper.

Finally, it may be noted that the phase transitions reported in this paper share analogies (but also differences) with phase transitions observed in the Hamiltonian mean-field (HMF) model [33–38], the spherical mass shell model [39], the Blume-Emery-Griffiths model [40], the infinite-range attactive interaction (IRAI) model [41], the self-gravitating Fermi gas model [28], the self-gravitating ring model [42] and the one-dimensional static cosmology model [43] (see review in [44]).

# II. KINETIC MODELS AND STATISTICAL EQUILIBRIUM STATES

## A. Isolated systems

We consider an isolated system of N particles in interaction described by the Hamiltonian equations

$$m\frac{d\mathbf{r}_i}{dt} = \frac{\partial H}{\partial \mathbf{v}_i}, \quad m\frac{d\mathbf{v}_i}{dt} = -\frac{\partial H}{\partial \mathbf{r}_i},$$
 (1)

where

$$H = \sum_{i} \frac{1}{2} m v_i^2 + m^2 \sum_{i < j} u(\mathbf{r}_i, \mathbf{r}_j) + m \sum_{i} V(\mathbf{r}_i).$$
(2)

We assume that the particles interact through a binary potential  $u(\mathbf{r}, \mathbf{r}')$  that is symmetric with respect to the interchange of  $\mathbf{r}$  and  $\mathbf{r}'$ , and that they also evolve in a fixed external potential  $V(\mathbf{r})$ . Since the system is isolated, with strict conservation of energy and mass, the proper statistical ensemble is the microcanonical ensemble [9]. In this paper, we shall use a mean-field approach [45]. In the microcanonical ensemble, the statistical equilibrium state is obtained by maximizing the Boltzmann entropy at fixed mass and energy. We thus have to solve the maximization problem

$$\max_{f} \{S[f] | E[f] = E, M[f] = M\},$$
(3)

with

$$S = -k_B \int \frac{f}{m} \ln \frac{f}{m} d\mathbf{r} d\mathbf{v}, \qquad (4)$$

$$M = \int \rho d\mathbf{r},$$
 (5)

$$E = \int f \frac{v^2}{2} d\mathbf{r} d\mathbf{v} + \frac{1}{2} \int \rho(\mathbf{r}, t) u(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}', t) d\mathbf{r} d\mathbf{r}' + \int \rho V d\mathbf{r},$$
(6)

where  $\rho(\mathbf{r}, t) = \int f(\mathbf{r}, \mathbf{v}, t) d\mathbf{v}$  is the spatial density. Introducing the mean-field potential

$$\Phi(\mathbf{r}) = \int u(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}') d\mathbf{r}' + V(\mathbf{r}), \qquad (7)$$

the energy can also be written as

$$E = \frac{1}{2} \int f v^2 d\mathbf{r} d\mathbf{v} + \frac{1}{2} \int \rho(\Phi + V) d\mathbf{r}.$$
 (8)

We shall be interested in global and local entropy maxima. Let us first determine the critical points of entropy at fixed mass and energy which cancel the first order variations. Introducing Lagrange multipliers, they satisfy

$$\delta S - \frac{1}{T} \delta E - \alpha \delta M = 0.$$
<sup>(9)</sup>

The variations are straightforward to evaluate and we obtain the mean field Maxwell-Boltzmann distribution

$$f = A e^{-\beta m [(v^2/2) + \Phi]},$$
(10)

where  $\beta = 1/k_BT$  and  $\Phi(\mathbf{r})$  is given by Eq. (7). Integrating over the velocity, the find that the density is given by the mean-field Boltzmann distribution

$$\rho = A' e^{-m\Phi/k_B T}.$$
(11)

These two expressions can be combined to give

$$f(\mathbf{r}, \mathbf{v}) = \left(\frac{m}{2\pi k_B T}\right)^{d/2} \rho(\mathbf{r}) e^{-mv^2/2k_B T}.$$
 (12)

This critical point is a (local) entropy maximum at fixed mass and energy if and only if (see, e.g., [47])

$$-\int \frac{(\delta f)^2}{2mf} d\mathbf{r} d\mathbf{v} - \frac{1}{2k_B T} \int \delta \rho \,\delta \Phi d\mathbf{r} \le 0, \qquad (13)$$

for all perturbations  $\delta f$  that conserve mass and energy at first order. In Appendix A, we provide an equivalent but simpler condition of stability in the microcanonical ensemble [see inequality (A13)].

The time evolution of the distribution function  $f(\mathbf{r}, \mathbf{v}, t)$  is governed by a kinetic equation of the form

$$\frac{\partial f}{\partial t} + \mathbf{v} \cdot \frac{\partial f}{\partial \mathbf{v}} - \nabla \Phi \cdot \frac{\partial f}{\partial \mathbf{r}} = \left(\frac{\partial f}{\partial t}\right)_{coll},\tag{14}$$

where

$$\Phi(\mathbf{r},t) = \int u(\mathbf{r},\mathbf{r}')\rho(\mathbf{r}',t)d\mathbf{r}' + V(\mathbf{r})$$
(15)

is the time-dependent mean-field potential. The left-hand side is an advective operator (Vlasov) in phase space. The right-hand side is a "collision" operator like the Boltzmann operator in the kinetic theory of gases or like the Landau (or

051103-2

Lenard-Balescu) operator in plasma physics or stellar dynamics. The collision operator in Eq. (14) takes into account the development of correlations between particles. It can have a more or less complicated form but it satisfies general properties associated with the first and second principles of thermodynamics: (i) it conserves mass and energy and (ii) it satisfies an H theorem for the Boltzmann entropy (4), i.e.,  $\dot{S} \ge 0$  with an equality if and only if f is the Maxwell-Boltzmann distribution (10). Furthermore, the Maxwell-Boltzmann distribution is dynamically stable if and only if it is a (local) entropy maximum at fixed mass and energy. These general properties can be checked directly for the Boltzmann equation, for the Landau equation, for the Lenard-Balescu equation, and for the BGK operator. Therefore, the kinetic equation (14) is consistent with the maximization problem (3) describing the statistical equilibrium state of the system in MCE. If we neglect the collisions for sufficiently short times, Eq. (14) reduces to the Vlasov equation which can experience a complicated process of collisionless violent relaxation towards a quasi stationary state (QSS) [48].

*Remark.* The maximization problem (3) also provides a sufficient condition of dynamical stability for isothermal distributions with respect to the Vlasov equation [49].

## B. Dissipative systems in phase space

We consider a dissipative system of N Brownian particles in interaction described by the Langevin equations

$$m\frac{d\mathbf{r}_i}{dt} = \frac{\partial H}{\partial \mathbf{v}_i},\tag{16}$$

$$\frac{d\mathbf{v}_i}{dt} = -\frac{1}{m}\frac{\partial H}{\partial \mathbf{r}_i} - \xi \mathbf{v}_i + \sqrt{2D}\mathbf{R}_i(t), \qquad (17)$$

where *H* is the Hamiltonian defined by Eq. (2),  $-\xi \mathbf{v}_i$  is a friction force, and  $\mathbf{R}_i(t)$  is a white noise satisfying  $\langle \mathbf{R}_i(t) \rangle = 0$  and  $\langle R_i^{\mu}(t)R_j^{\nu}(t) \rangle = \delta_{ij}\delta_{u\nu}\delta(t-t')$ . The diffusion coefficient *D* and the friction coefficient  $\xi$  are related to each other according to the Einstein relation  $\xi = D\beta m$ , where  $\beta = 1/(k_BT)$  is the inverse temperature. Since this system is dissipative, the proper statistical ensemble is the canonical ensemble [9]. In the canonical ensemble, the statistical equilibrium state is obtained by minimizing the Boltzmann free energy F[f] = E[f] - TS[f] at fixed mass. We thus have to solve the minimization problem

$$\min_{f} \{F[f] | M[f] = M\},$$
(18)

with

$$F = \int f \frac{v^2}{2} d\mathbf{r} d\mathbf{v} + \frac{1}{2} \int \rho(\mathbf{r}, t) u(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}', t) d\mathbf{r} d\mathbf{r}' + \int \rho V d\mathbf{r} + k_B T \int \frac{f}{m} \ln \frac{f}{m} d\mathbf{r} d\mathbf{v}.$$
 (19)

We shall be interested by global and local minima of free energy. Let us first determine the critical points of free energy at fixed mass which cancel the first-order variations. Introducing a Lagrange multiplier, they satisfy

$$\delta F + \alpha T \delta M = 0. \tag{20}$$

The variations are straightforward to evaluate and we obtain the mean-field Maxwell-Boltzmann distribution (10) and the mean-field Boltzmann distribution (11) as in the microcanonical ensemble. This critical point is a (local) minimum of free energy if and only if

$$\delta^2 F = \frac{1}{2} \int \delta \rho \,\delta \Phi \, d\mathbf{r} + \frac{k_B T}{m} \int \frac{(\delta f)^2}{2f} d\mathbf{r} \, d\mathbf{v} \ge 0 \qquad (21)$$

for all perturbations  $\delta f$  that conserve mass. In Appendix A, we provide an equivalent but simpler condition of stability in the canonical ensemble [see inequality (A28)].

In the mean-field approximation, the evolution of the distribution function  $f(\mathbf{r}, \mathbf{v}, t)$  is governed by a kinetic equation of the form

$$\frac{\partial f}{\partial t} + \mathbf{v} \cdot \frac{\partial f}{\partial \mathbf{v}} - \nabla \Phi \cdot \frac{\partial f}{\partial \mathbf{r}} = \frac{\partial}{\partial \mathbf{v}} \left( D \frac{\partial f}{\partial \mathbf{v}} + \xi f \mathbf{v} \right), \qquad (22)$$

coupled to the mean-field potential (15). This is called the mean-field Kramers equation. The mean-field Kramers equation conserves mass and satisfies an *H* theorem for the Boltzmann free energy (19), i.e.,  $\dot{F} \leq 0$  with an equality if and only if *f* is the Maxwell-Boltzmann distribution (10). Furthermore, the Maxwell-Boltzmann distribution is dynamically stable if and only if it is a (local) minimum of free energy at fixed mass. Therefore, the kinetic equation (22) is consistent with the minimization problem (18) describing the statistical equilibrium state of the system in CE.

*Remark.* The critical points in MCE and CE are the same because the variational problems (3) and (18) are equivalent at the level of the first-order variations (9) and (20). However, they are not equivalent at the level of the second-order variations (13) and (21) because of the different class of perturbations to consider. Therefore, we can have *ensembles inequivalence* [22,32,50,51]. In fact, the condition of canonical stability (18) provides a *sufficient* condition of microcanonical stability (3). Indeed, if inequality (21) is satisfied for all perturbations that conserve mass, then it is *a fortiori* satisfied for perturbations that conserve mass *and* energy so that inequality (13) is satisfied. Therefore, canonical stability implies microcanonical stability,

$$(18) \Rightarrow (3). \tag{23}$$

However, the converse is wrong in case of ensembles inequivalence.

#### C. Dissipative systems in physical space

In the strong friction limit  $\xi \rightarrow +\infty$ , we can formally neglect the inertial term  $d\mathbf{v}_i/dt$  in Eq. (17) and we obtain the overdamped Langevin equations

$$\xi \frac{d\mathbf{r}_i}{dt} = -\frac{1}{m} \frac{\partial H}{\partial \mathbf{r}_i} + \sqrt{2D} \mathbf{R}_i(t).$$
(24)

The statistical equilibrium state of this system (described by the canonical ensemble [9]) is obtained by solving the minimization problem

$$\min_{\rho} \{ F[\rho] | M[\rho] = M \},$$
(25)

with

$$F = \frac{1}{2} \int \rho(\mathbf{r}, t) u(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}', t) d\mathbf{r} d\mathbf{r}' + \int \rho V d\mathbf{r} + k_B T \int \frac{\rho}{m} \ln \frac{\rho}{m} d\mathbf{r}.$$
 (26)

Writing the variational principle as

$$\delta F + \alpha T \delta M = 0, \qquad (27)$$

we obtain the mean-field Boltzmann distribution (11). This critical point is a (local) minimum of free energy at fixed mass if and only if

$$\delta^2 F = \frac{1}{2} \int \delta \rho \,\delta \Phi \,d\mathbf{r} + \frac{k_B T}{m} \int \frac{(\delta \rho)^2}{2\rho} d\mathbf{r} \ge 0 \qquad (28)$$

for all perturbations  $\delta \rho$  that conserves mass.

In the mean-field approximation, the evolution of the density profile  $\rho(\mathbf{r}, t)$  is governed by a kinetic equation of the form

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left[ \frac{1}{\xi} \left( \frac{k_B T}{m} \nabla \rho + \rho \nabla \Phi \right) \right], \tag{29}$$

coupled to the mean-field equation (15). This is called the mean-field Smoluchowski equation. The mean-field Smoluchowski equation (29) conserves mass and satisfies an H theorem for the Boltzmann free energy (26), i.e.,  $\dot{F} \leq 0$  with an equality if and only if  $\rho$  is the Boltzmann distribution (11). Furthermore, the Boltzmann distribution is dynamically stable if and only if it is a (local) minimum of free energy at fixed mass. Therefore, the kinetic equation (29) is consistent with the minimization problem (25) describing the statistical equilibrium state of the system in CE.

*Remark 1.* The Smoluchowski equation (29) can also be deduced from the Kramers equation (22) in the strong friction limit [52]. For  $\xi, D \rightarrow +\infty$  and  $\beta = \xi/Dm$  finite, the time-dependent distribution function  $f(\mathbf{r}, \mathbf{v}, t)$  is Maxwellian

$$f(\mathbf{r},\mathbf{v},t) = \left(\frac{\beta m}{2\pi}\right)^{d/2} \rho(\mathbf{r},t)e^{-\beta m(v^2/2)} + O(1/\xi), \quad (30)$$

and the time-dependent density  $\rho(\mathbf{r}, t)$  is solution of the Smoluchowski equation (29). Using Eq. (30), we can express the free energy (19) as a functional of the density and we obtain the free energy (26) up to some unimportant constants.

*Remark 2.* It is shown in Appendix A that the maximization problems (18) and (25) are equivalent in the sense that  $f(\mathbf{r}, \mathbf{v})$  is solution of (18) if and only if  $\rho(\mathbf{r})$  is solution of (25). Thus, we have

$$(18) \Leftrightarrow (25). \tag{31}$$

As a consequence, the Maxwell-Boltzmann distribution  $f(\mathbf{r}, \mathbf{v})$  is dynamically stable with respect to the mean field Kramers equation (22) if and only if the corresponding Boltzmann distribution  $\rho(\mathbf{r})$  is dynamically stable with respect to the mean-field Smoluchowski equation (29). On the other hand, according to implication (23), the Maxwell-Boltzmann distribution  $f(\mathbf{r}, \mathbf{v})$  is dynamically stable with respect to the kinetic equation (14) if it is stable with respect to the mean-field Kramers equation (22), but the reciprocal is wrong in case of ensembles inequivalence.

*Remark 3.* The minimization problem (25) also provides a necessary and sufficient condition of dynamical stability for isothermal distributions with respect to the barotropic Euler equation [49].

## D. Keller-Segel model of chemotaxis

The Keller-Segel model [3] describing the chemotaxis of biological populations can be written as

$$\frac{\partial \rho}{\partial t} = \nabla \cdot (D \nabla \rho - \chi \rho \nabla c), \qquad (32)$$

$$\frac{1}{D'}\frac{\partial c}{\partial t} = \Delta c - k^2 c + \lambda \rho, \qquad (33)$$

where  $\rho$  is the concentration of the biological species (e.g., bacteria) and *c* is the concentration of the secreted chemical. The bacteria diffuse with a diffusion coefficient *D* and undergo a chemotactic drift with strength  $\chi$  along the gradient of chemical. The chemical is produced by the bacteria at a rate  $D'\lambda$ , is degraded at a rate  $D'k^2$ , and diffuses with a diffusion coefficient *D'*. We adopt Neumann boundary conditions [3]

$$\nabla c \cdot \mathbf{n} = 0, \quad \nabla \rho \cdot \mathbf{n} = 0, \tag{34}$$

where **n** is a unit vector normal to the boundary of the domain. With these boundary conditions, the conservation of mass is automatically satisfied. The drift-diffusion equation (32) is similar to the mean-field Smoluchowski equation (29) where the concentration of chemical  $-c(\mathbf{r},t)$  plays the role of the potential  $\Phi(\mathbf{r},t)$ . Therefore, there exists many analogies between chemotaxis and Brownian particles in interaction [6]. In particular, the effective statistical ensemble associated with the Keller-Segel model is the canonical ensemble. The steady states of the Keller-Segel model are of the form

$$\rho = A e^{(\chi/D)c},\tag{35}$$

which is similar to the Boltzmann distribution (11) with an effective temperature  $T_{eff}=D/\chi$ . The Lyapunov functional associated with the KS model is [4]

$$F = \frac{1}{2\lambda} \int \left[ (\nabla c)^2 + k^2 c^2 \right] d\mathbf{r} - \int \rho c d\mathbf{r} + T_{eff} \int \rho \ln \rho d\mathbf{r}.$$
(36)

It is similar to a free energy  $F=E-T_{eff}S$  in thermodynamics, where E is the energy and S is the Boltzmann entropy. The KS model conserves mass and satisfies an *H* theorem for the free energy (36), i.e.,  $\dot{F} \leq 0$  with an equality if and only if  $\rho$  is the Boltzmann distribution (35). Furthermore, the Boltzmann distribution is dynamically stable if and only if it is a (local) minimum of free energy at fixed mass. In that context, the minimization problem

$$\min_{\rho,c} \{F[\rho,c] | M[\rho] = M\}$$
(37)

determines a steady state of the KS model that is dynamically stable. This is similar to a condition of thermodynamical stability in the canonical ensemble.

Let us consider some simplified forms of the Keller-Segel model that have been introduced in the literature.

(i) In the limit of large diffusivity of the chemical  $D' \rightarrow +\infty$  at fixed  $k^2$  and  $\lambda$ , the reaction-diffusion equation (33) takes the form of a screened Poisson equation [8],

$$\Delta c - k^2 c = -\lambda \rho, \qquad (38)$$

and the free energy becomes

$$F = -\frac{1}{2} \int \rho c d\mathbf{r} + T_{eff} \int \rho \ln \rho d\mathbf{r}.$$
 (39)

In that case, the KS model is isomorphic to the Smoluchowski equation (29) with an attractive Yukawa potential (65).

(ii) In the limit of large diffusivity of the chemical  $D' \rightarrow +\infty$  and a vanishing degradation rate  $k^2=0$ , the reactiondiffusion equation (33) takes the form of a modified Poisson equation [11],

$$\Delta c = -\lambda(\rho - \overline{\rho}), \tag{40}$$

where  $\overline{\rho} = M/V$  is the average density, and the free energy becomes

$$F = -\frac{1}{2} \int (\rho - \overline{\rho}) c d\mathbf{r} + T_{eff} \int \rho \ln \rho d\mathbf{r}.$$
 (41)

In that case, the KS model is isomorphic to the Smoluchowski equation (29) with a modified Poisson equation (44).

(iii) Some authors have also considered a simple model of chemotaxis where the reaction-diffusion equation (33) is replaced by the Poisson equation [53],

$$\Delta c = -\lambda \rho. \tag{42}$$

This is valid in the absence of degradation of the chemical and for sufficiently large densities  $\rho \gg \overline{\rho}$ . This model can be used in particular to study chemotactic collapse. The corresponding free energy is

$$F = -\frac{1}{2} \int \rho c d\mathbf{r} + T_{eff} \int \rho \ln \rho d\mathbf{r}.$$
 (43)

In that model, the boundary conditions (34) must be modified [54] and we must impose that *c* behaves at infinity like the gravitational potential in astrophysics. Furthermore, we must impose that the normal component of the current vanishes on the boundary:  $(D\nabla \rho - \chi \rho \nabla c) \cdot \mathbf{n} = 0$  so as to conserve mass. In that case, the KS model is isomorphic to the SP system describing self-gravitating Brownian particles in the overdamped limit [29].

# E. Physical justification of the canonical ensemble for systems with long-range interactions

In statistical mechanics, the canonical distribution is usually derived by considering a subpart of a large system and assuming that the rest of the system plays the role of a thermostat [55]. However, this justification implicitly assumes that energy is additive. Since energy is *nonadditive* for systems with long-range interactions, it is sometimes concluded that the canonical ensemble has no foundation to describe systems with long-range interactions [56]. In fact, this is not quite true [9]. We can give two justifications of the canonical ensemble for systems with long-range interactions:

(i) The canonical ensemble is relevant to describe a system of particles in contact with a thermal bath of a *different* nature [9]. This is the case if we consider a system of Brownian particles in interaction described by the stochastic equations (16) and (17). The particles interact through a potential  $u(\mathbf{r}, \mathbf{r}')$  that can be long-range, but they also undergo a friction force and a stochastic force that are due to other types of interaction (they model in general short-range interactions). As we have seen, this system is described by the canonical ensemble. It does not correspond to a subsystem of a larger system but simply to a system as a whole with long-range and short-range interactions [59].

(ii) Since canonical stability implies microcanonical stability [50], the condition of canonical stability provides a *sufficient* condition of microcanonical stability. In this sense, the study of the minimization problems (18) and (25), and the corresponding canonical stability criteria (see Secs. II B and II C) can be useful even for an isolated Hamiltonian system (see Sec. II A) because if we can prove that this system is canonically stable, then it is granted to be microcanonically stable. This remark also applies to other ensembles (grand canonical, grand microcanonical, etc.) [31].

# **III. MODIFIED NEWTONIAN MODEL**

In this section, we discuss phase transitions that appear in the modified Newtonian model.

#### A. Physical motivation of the model

We consider a system of particles interacting via a mean field potential  $\Phi(\mathbf{r}, t)$  that is solution of the modified Poisson equation

$$\Delta \Phi = S_d G(\rho - \bar{\rho}), \qquad (44)$$

where  $\bar{\rho} = M/V$  is the average density (conserved quantity). At statistical equilibrium, the density is given by the Boltzmann distribution

$$\rho = A e^{-\beta m \Phi}.$$
(45)

We have used the notations of astrophysics (where G is the constant of gravity and  $S_d$  the surface of a unit sphere in d

dimensions) in order to make the connection with ordinary self-gravitating systems where Eq. (44) is replaced by the Poisson equation  $\Delta \Phi = S_d G \rho$ . However, this model can have application in other contexts as explained below. We assume that the system is confined in a finite domain (box) and we impose the Neumann boundary conditions

$$\nabla \Phi \cdot \mathbf{n} = 0, \quad \nabla \rho \cdot \mathbf{n} = 0, \tag{46}$$

where **n** is a unit vector normal to the boundary of the box (the explicit expression of the potential in d=1 is given in Appendix B). This model admits spatially homogeneous solutions ( $\rho = \overline{\rho}$  and  $\Phi = 0$ ) at any temperature. It also admits spatially inhomogeneous solutions at sufficiently low temperatures. We shall study this model in arbitrary dimensions of space d with explicit computations for d=1,2,3. This model has different physical applications.

(i) It describes self-gravitating systems in a cosmological setting [12]. When we take into account the expansion of the universe and work in the comoving frame, the usual Poisson equation  $\Delta \Phi = 4\pi G\rho$  is replaced by an equation of the form  $\Delta \phi = 4\pi Ga(t)^2 [\rho(\mathbf{x},t) - \rho_b(t)]$  where the potential is produced by the deviation between the actual density  $\rho(\mathbf{x},t)$  and the mean density  $\rho_b(t)$ . This is similar to the effect of a "neutralizing background" in plasma physics. Furthermore, the Hamiltonian equations of motion read  $(d/dt)(ma^2\dot{\mathbf{x}}) =$  $-m\nabla\phi$ . In cosmology, we must account for the evolution of the scale factor a(t) but if we consider time scales that are short with respect to the Hubble time  $H^{-1} = a/\dot{a}$ , we can ignore this time dependence and we obtain a model similar to Eq. (44). This model has been studied by Valageas [43] in d=1 with periodic boundary conditions. In that context, the relevant ensemble is the MCE since the system is isolated.

(ii) By a proper reinterpretation of the parameters, the field equation (44) describes the relation between the concentration of the chemical and the density of bacteria in the Keller-Segel model (32)–(40). In that case, the most physical dimension is d=2 and the boundary conditions are of form (46). Furthermore, the relevant ensemble is the CE since the KS model has a canonical structure. This model has been studied by applied mathematicians, starting with Jäger and Luckhaus [11], but they have not performed the type of study that we are developing in this paper. In view of these different applications, we shall study this model in the microcanonical and canonical ensembles in any dimension of space.

#### **B.** Modified Emden equation

In the modified Newtonian model, the statistical equilibrium state is given by the Boltzmann distribution (45) coupled to the modified Poisson equation (44). We look for spherically symmetric solutions because, for non rotating systems, entropy maxima (or minima of free energy) are spherically symmetric. Introducing the central density  $\rho_0 = \rho(0)$ , the central potential  $\Phi_0 = \Phi(0)$ , the new field  $\psi = \beta m (\Phi - \Phi_0)$ , and the scaled distance  $\xi = (S_d G \beta m \rho_0)^{1/2} r$ , the Boltzmann distribution (45) can be rewritten as

$$\rho = \rho_0 e^{-\psi(\xi)}.\tag{47}$$

Substituting this relation in the modified Poisson equation (44), we obtain the modified Emden equation



FIG. 1. The function  $e^{-\psi}$  for d=1 and  $\lambda=0.5<1$  (bottom) or  $\lambda=2>1$  (top). In d=1, the oscillations are undamped.

$$\frac{1}{\xi^{d-1}}\frac{d}{d\xi}\left(\xi^{d-1}\frac{d\psi}{d\xi}\right) = e^{-\psi} - \lambda, \tag{48}$$

where  $\lambda = \overline{\rho}/\rho_0$  plays the role of the inverse central density. Since  $\Phi'(0)=0$  for a spherically symmetric system, the boundary conditions at the origin are

$$\psi(0) = \psi'(0) = 0. \tag{49}$$

The ordinary Emden equation [60] is recovered for  $\lambda = 0$ , i.e., for very large central densities with respect to the average density. The function  $e^{-\psi(\xi)}$  is plotted in Figs. 1 and 2 for different values of  $\lambda$  and different dimensions of space *d*. It presents an infinity of oscillations. For d=1, the oscillations are undamped and their period is given by Eq. (E11). For  $d \ge 2$ , the oscillations are damped and the function  $\psi(\xi)$  tends to the asymptotic value  $-\ln \lambda$  for  $\xi \rightarrow +\infty$ .

We assume that the system is enclosed in a spherical box of radius *R*. The normalized box radius  $\alpha = (S_d G \beta m \rho_0)^{1/2} R$  is determined by the boundary condition  $\Phi'(R) = 0$  that becomes

$$\psi'(\alpha) = 0. \tag{50}$$

For a given value of  $\lambda$ , we need to integrate the modified Emden equation (48) and (49) until the point  $\xi = \alpha$  such that



FIG. 2. The function  $e^{-\psi}$  for d=2 and  $\lambda=0.5<1$  (bottom) or  $\lambda=2>1$  (top). In  $d\geq 2$ , the oscillations are damped. The case d=3 (not represented) is similar.



FIG. 3. Inverse temperature  $\eta$  as a function of the central density  $1/\lambda$  for the first three branches in d=1.

 $\psi'(\alpha)=0$ . Since the function  $\psi(\xi)$  presents an infinite number of oscillations, this determines an infinity of solutions  $\alpha_1(\lambda), \alpha_2(\lambda), \ldots$  that will correspond to different branches in the following diagrams. Once  $\alpha_n(\lambda)$  is determined, the density profile is given by Eq. (47). The density profile is extremum at the center and at the boundary. On the *n*th branch, the density profile shows *n* "clusters" corresponding to the oscillations of  $e^{-\psi(\xi)}$ . Close to the origin, the density increases for  $\lambda > 1$  while it decreases for  $\lambda < 1$ . The homogeneous state  $\psi=0$  corresponds to  $\lambda=1$ . This solution is degenerate because the boundary condition (50) is satisfied for any  $\alpha$ .

Remark. When  $\lambda \rightarrow 0$ , corresponding to large values of the central density, we expect to obtain results similar to those obtained for the usual Newtonian model since the differential equation (48) reduces to the ordinary Emden equation. However, the results are different because the boundary conditions are not the same. In the Newtonian model, the force at the boundary is nonzero [for a spherically symmetric system, according to the Gauss theorem, we have  $\Phi'(R) = GM/R^{d-1}$ ], while in the modified Newtonian model the force at the boundary is zero [ $\Phi'(R)=0$ ]. Therefore, strictly speaking, the Newtonian and the modified Newtonian models behave differently even when  $\rho_0 \rightarrow +\infty$ . Nevertheless, for large central concentrations, the Newtonian solution provides a good approximation of the modified Newtonian solution in the core (see Appendix E).

#### **C.** Temperature

We must now relate the normalized central density  $1/\lambda$  to the temperature *T*. Recalling that  $\overline{\rho} = M/V$  with  $V = \frac{1}{d}S_dR^d$ , we obtain

$$\lambda = \frac{\overline{\rho}}{\rho_0} = \frac{dM}{S_d R^d} \frac{1}{\rho_0} = d\frac{GMm\beta}{R^{d-2}} \frac{1}{\alpha^2}.$$
 (51)

Introducing the normalized inverse temperature

$$\eta \equiv \frac{\beta GMm}{R^{d-2}},\tag{52}$$

we find the relation





FIG. 4. Inverse temperature  $\eta$  as a function of the central density  $1/\lambda$  for the first three branches in d=2.

$$\eta = \frac{1}{d} \lambda \alpha^2.$$
 (53)

Recalling that  $\alpha = \alpha_n(\lambda)$  for the *n*th branch, this equation gives the relation between the inverse temperature  $\eta$  and the central density  $1/\lambda$  for the *n*th branch. In Figs. 3–5, we plot the inverse temperature  $\eta$  as a function of the central density  $1/\lambda$  for the first three branches n=1,2,3 in different dimensions of space d=1,2,3.

Let us discuss the asymptotic behaviors of the temperature (we only describe the first branch n=1) and compare with the Newtonian model (see, e.g., [29]).

(i) In d=1: for the ordinary Newtonian model, the series of equilibria is parametrized by  $\alpha$ , which is a measure of the central density. When  $\alpha \rightarrow +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(x)$  and the inverse temperature  $\eta \rightarrow +\infty$ . When  $\alpha \rightarrow 0$ , the distribution is homogeneous and the inverse temperature  $\eta \rightarrow 0$ . For the modified Newtonian model, the series of equilibria is parametrized by the central density  $1/\lambda$ . When  $1/\lambda \rightarrow +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(x)$  and  $\eta \rightarrow +\infty$  with the same asymptotic behavior as in the Newtonian model (see Appendix E). When  $\lambda = 1$ , the distribution is homogeneous and  $\eta = \eta_c^* = \pi^2 \approx 9.869\ 604\ 4$ (see Appendix F). When  $1/\lambda \rightarrow 0$ , the distribution tends to a



FIG. 5. Inverse temperature  $\eta$  as a function of the central density  $1/\lambda$  for the first three branches in d=3.

Dirac peak  $\rho = \frac{M}{2} [\delta(x-R) + \delta(x+R)]$  concentrated at the box and  $\eta \to +\infty$ .

(ii) In d=2: for the ordinary Newtonian model, the series of equilibria is parametrized by  $\alpha$ . When  $\alpha \to +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(\mathbf{r})$  and the inverse temperature tends to  $\eta_c = 4$ . When  $\alpha \to 0$ , the distribution is homogeneous and the inverse temperature  $\eta \to 0$ . For the modified Newtonian model, the series of equilibria is parametrized by  $1/\lambda$ . When  $1/\lambda \to +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(\mathbf{r})$  and  $\eta \to \eta_c = 4$  (since the density is very much concentrated, the boundary conditions do not matter and we recover the same results as in the Newtonian case). When  $\lambda = 1$ , the distribution is homogeneous and  $\eta$  $= \eta_c^* = \frac{1}{2}j_{11}^2 \approx 7.341\,000\,8$  (see Appendix F). When  $1/\lambda \to 0$ , the distribution is concentrated at the boundary and  $\eta \to +\infty$ .

(iii) In d=3: for the ordinary Newtonian model, the series of equilibria is parametrized by  $\alpha$ . When  $\alpha \rightarrow +\infty$ , the distribution tends to the singular isothermal sphere  $\rho_s(r)$ =1/( $2\pi G\beta mr^2$ ) and the inverse temperature  $\eta \rightarrow \eta_s = 2$ . The curve  $\eta(\alpha)$  displays damped oscillations around this value. When  $\alpha \rightarrow 0$ , the distribution is homogeneous and the inverse temperature  $\eta \rightarrow 0$ . For the modified Newtonian model, the series of equilibria is parametrized by  $1/\lambda$ . When  $1/\lambda \rightarrow$  $+\infty$ , the distribution is concentrated at the center and we numerically find that  $\eta \rightarrow 3.05 \cdots$  (the value is different from the Newtonian result  $\eta_s = 2$  due to different boundary conditions and the fact that the profile extends up to the box). The curve  $\eta(\lambda)$  displays damped oscillations around this value. When  $\lambda = 1$ , the distribution is homogeneous and  $\eta = \eta_{a}^{*}$  $=\frac{1}{3}x_1^2 \simeq 6.730\ 244\ 5$  (see Appendix F). When  $1/\lambda \rightarrow 0$ , the distribution is concentrated at the boundary and we numerically find that  $\eta \rightarrow +\infty$ .

## **D. Energy**

We must also relate the normalized central density  $1/\lambda$  to the energy *E*. The total energy is given by (see Appendix C)

$$E = \int f \frac{v^2}{2} d\mathbf{r} d\mathbf{v} + \frac{1}{2} \int (\rho - \overline{\rho}) \Phi d\mathbf{r}.$$
 (54)

Using the Maxwell-Boltzmann distribution (10), the kinetic energy is simply

$$K = \frac{d}{2}Nk_BT.$$
 (55)

Using the modified Poisson equation (44) and an integration by parts, the potential energy can be written as

$$W = -\frac{1}{2S_d G} \int (\nabla \Phi)^2 d\mathbf{r}.$$
 (56)

The total energy E = K + W is therefore given by

$$E = \frac{d}{2}Nk_BT - \frac{1}{2S_dG}\int (\nabla\Phi)^2 d\mathbf{r}.$$
 (57)

Introducing the dimensionless variables defined previously, recalling that  $r = \xi R / \alpha$ , and introducing the normalized energy



FIG. 6. Energy  $\Lambda$  as a function of the central density  $1/\lambda$  for the first three branches in d=1.

$$\Lambda = -\frac{ER^{d-2}}{GM^2},\tag{58}$$

we obtain

$$\Lambda = -\frac{d}{2\eta} + \frac{1}{2\eta^2} \frac{1}{\alpha^{d-2}} \int_0^\alpha \left(\frac{d\psi}{d\xi}\right)^2 \xi^{d-1} d\xi.$$
 (59)

Recalling that  $\alpha = \alpha_n(\lambda)$  and  $\eta = \eta_n(\lambda)$  for the *n*th branch, this equation gives the relation between the energy  $\Lambda$  and the central density  $1/\lambda$  for the *n*th branch.

In Figs. 6–8, we plot the normalized energy  $\Lambda$  as a function of the central density  $1/\lambda$  for the first three branches n = 1, 2, 3 in different dimensions of space d=1, 2, 3.

Let us consider the asymptotic behaviors of the energy (we only describe the first branch n=1) and compare with the Newtonian model (see, e.g., [29]).

(i) In d=1: for the ordinary Newtonian model, the series of equilibria is parametrized by  $\alpha$ , which is a measure of the central density. When  $\alpha \rightarrow +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(x)$  and the energy  $\Lambda \rightarrow 0$ . When  $\alpha \rightarrow 0$ , the distribution is homogeneous and the energy  $\Lambda \rightarrow -\infty$ . For the modified Newtonian model, the series of equilibria is parametrized by the central density  $1/\lambda$ . When  $1/\lambda \rightarrow +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(x)$  and  $\Lambda \rightarrow \Lambda_{max}^{(1)}$ = 1/6 (see Appendix D). When  $\lambda = 1$  the distribution is ho-



FIG. 7. Energy  $\Lambda$  as a function of the central density  $1/\lambda$  for the first three branches in d=2.



FIG. 8. Energy  $\Lambda$  as a function of the central density  $1/\lambda$  for the first three branches in d=3.

mogeneous and  $\Lambda = \Lambda_c^* = -1/(2\eta_c^*) \approx -0.050\ 660\ 6$ . When  $1/\lambda \to 0$ , the distribution tends to a Dirac peak  $\rho = \frac{M}{2} [\delta(x-R) + \delta(x+R)]$  concentrated at the box and  $\Lambda \to \Lambda_{max}^{(1)}$ .

(ii) In d=2: for the ordinary Newtonian model, the series of equilibria is parametrized by  $\alpha$ . When  $\alpha \to +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(\mathbf{r})$  and the energy  $\Lambda \to +\infty$ . When  $\alpha \to 0$ , the distribution is homogeneous and the energy  $\Lambda \to -\infty$ . For the modified Newtonian model, the series of equilibria is parametrized by  $1/\lambda$ . When  $1/\lambda \to +\infty$ , the distribution tends to a Dirac peak  $\rho = M \delta(\mathbf{r})$ and  $\Lambda \to +\infty$ . When  $\lambda = 1$  the distribution is homogeneous and  $\Lambda = \Lambda_c^* = -1/\eta_c^* \simeq -0.136\ 221\ 21$ . When  $1/\lambda \to 0$ , the distribution is concentrated at the boundary and we numerically find that  $\Lambda \to 0.1$ .

(iii) In d=3: for the ordinary Newtonian model, the series of equilibria is parametrized by  $\alpha$ . When  $\alpha \rightarrow +\infty$ , the distribution tends to the singular isothermal sphere  $\rho_s(r)$ =1/( $2\pi G\beta mr^2$ ) with energy  $\Lambda_s = 1/4$ . The curve  $\Lambda(\alpha)$  undergoes damped oscillations around this value. When  $\alpha \rightarrow 0$ , the distribution is homogeneous and the energy  $\Lambda \rightarrow -\infty$ . For the modified Newtonian model, the series of equilibria is parametrized by  $1/\lambda$ . When  $1/\lambda \rightarrow +\infty$ , the distribution is concentrated at the center and we numerically find that  $\Lambda$  $\rightarrow -0.38 \cdots$  (the value is different from the Newtonian result  $\Lambda_s = 1/4$  due to different boundary conditions and the fact that the profile extends up to the box). The curve  $\Lambda(\lambda)$  undergoes damped oscillations around this value. When  $\lambda = 1$ the distribution is homogeneous and  $\Lambda = \Lambda_a^* = -3/(2\eta_a^*) \simeq$ -0.222 874 52. When  $\lambda \rightarrow 0$ , the distribution is concentrated at the boundary and we numerically find that  $\Lambda \rightarrow 0.05$ .

## E. Entropy and free energy

Finally, we relate the central density  $1/\lambda$  to the entropy S and to the free energy F. Using Eqs. (4), (10), and (11), the entropy is given by

$$S = \frac{d}{2}Nk_B \ln T - k_B \int \frac{\rho}{m} \ln \frac{\rho}{m} d\mathbf{r}.$$
 (60)

Substituting Eq. (47) in Eq. (60), and introducing the dimensionless variables defined previously, we get



FIG. 9. Free energy  $\frac{J}{Nk_B}$  as a function of the inverse temperature  $\eta$  in d=1. Note that the branches  $\lambda < 1$  and  $\lambda > 1$  coincide.

$$\frac{S}{Nk_B} = -\frac{d}{2}\ln\beta - \ln\rho_0 + \frac{\rho_0}{Nm}S_d \left(\frac{R}{\alpha}\right)^d \int_0^\alpha \psi e^{-\psi} \xi^{d-1} d\xi$$
(61)

up to some unimportant constants. Using  $\alpha = (S_d G \beta m \rho_0)^{1/2} R$  to express  $\rho_0$  in terms of  $\alpha$  and introducing the normalized temperature (52), we finally obtain

$$\frac{S}{Nk_B} = -\frac{d-2}{2} \ln \eta - 2 \ln \alpha + \frac{1}{\eta} \frac{1}{\alpha^{d-2}} \int_0^\alpha \psi e^{-\psi} \xi^{d-1} d\xi,$$
(62)

up to some unimportant constants. Using the previous results, this expression relates the entropy  $S/Nk_B$  to the central density  $1/\lambda$ . The free energy is F=E-TS. In the following, it will be more convenient to work in terms of the Massieu function  $J=S-k_B\beta E$  (by an abuse of language, we shall often refer to J as the free energy). We have

$$\frac{J}{Nk_B} = \frac{S}{Nk_B} + \eta \Lambda.$$
(63)

Using the previous results, this expression relates the free energy  $J/Nk_B$  to the central density  $1/\lambda$ .

In Figs. 9–11, we have plotted the free energy  $J/Nk_B$  as a function of the inverse temperature  $\eta$  (parametrized by the



FIG. 10. Free energy  $\frac{J}{Nk_B}$  as a function of the inverse temperature  $\eta$  in d=2.



FIG. 11. Free energy  $\frac{J}{Nk_B}$  as a function of the inverse temperature  $\eta$  in d=3.

central density  $1/\lambda$ ) in d=1,2,3. In Figs. 12–15, we have plotted the entropy  $S/Nk_B$  as a function of the energy  $\Lambda$ (parametrized by the central density  $1/\lambda$ ) in d=1,2,3. In these figures, the solid lines without label refer to the homogeneous phase. The solid lines with label n=1 refer to the first inhomogeneous branch. The dashed lines with label n=2 refer to the second inhomogeneous branch. These curves will be helpful in the next section to analyze the phase transitions in the canonical and microcanonical ensembles respectively.

*Remark.* Since  $\delta S = k_B \beta \delta E$ , the extrema of entropy  $S(\lambda)$ and energy  $E(\lambda)$  coincide. Since the series of equilibria  $E(\lambda)$ exhibits damped oscillations for  $1/\lambda \rightarrow +\infty$  in d=3 (see Fig. 8), this implies that the curve  $S(\lambda)$  will also exhibit damped oscillations at the same locations. Correspondingly, S(E) will present some "spikes" for  $1/\lambda \rightarrow +\infty$  in d=3 (see inset of Fig. 15). Similarly, since  $\delta J = -Ek_B \delta \beta$ , the extrema of free energy  $J(\lambda)$  and temperature  $\beta(\lambda)$  coincide. Since the series of equilibria  $\beta(\lambda)$  exhibits damped oscillations for  $1/\lambda \rightarrow +\infty$  in d =3 (see Fig. 5), this implies that the curve  $J(\lambda)$  will also exhibit damped oscillations at the same location, and that the curve  $J(\beta)$  will present some "spikes" for  $1/\lambda \rightarrow +\infty$  in d =3 (see inset of Fig. 11). In addition, the curve  $J(\beta)$  presents a minimum for  $\eta \simeq 24.7$  corresponding to E=0. Similar behaviors were previously observed in the model of selfgravitating fermions [28,32].



FIG. 12. Entropy  $\frac{S}{Nk_B}$  as a function of energy  $\Lambda$  in d=1. Note that the branches  $\lambda < 1$  and  $\lambda > 1$  coincide.



FIG. 13. Entropy  $\frac{S}{Nk_{P}}$  as a function of energy  $\Lambda$  in d=2.

#### F. Caloric curves and phase transitions

We shall now determine the caloric curve  $\beta(E)$  corresponding to the modified Newtonian model. First of all, we note that for the homogeneous phase, the potential energy W=0 so that the energy reduces to the kinetic energy. Therefore, the series of equilibria of the homogeneous phase is simply

$$\eta = -\frac{d}{2\Lambda}.$$
(64)

On the other hand, eliminating  $\lambda$  between  $\eta_n(\lambda)$  and  $\Lambda_n(\lambda)$  given by Eqs. (53) and (59), we get the series of equilibria  $\eta_n(\Lambda)$  for the *n*th inhomogeneous branch. The series of equilibria contain all the critical points of the optimization problems (3) and (18). The series of equilibria are the same in the canonical and microcanonical ensembles because the critical points are the same. They contain fully stable states (global maxima of *S* or *J*), metastable states (local maxima of *S* or *J*), metastable states (local maxima of *S* or *J*), and unstable states (saddle points of *S* or *J*). The stable parts of the series of equilibria form the caloric curves in the canonical and microcanonical ensembles. We shall distinguish the strict caloric curves formed by fully stable states and the physical caloric curves containing fully stable and



FIG. 14. Enlargement of Fig. 13. The entropies of the homogeneous phase and inhomogeneous phase become equal at  $\Lambda = \Lambda_I \approx$  -0.146. This corresponds to a first-order phase transition in the microcanonical ensemble marked by the discontinuity of the slope S'(E)=1/T.



FIG. 15. Entropy  $\frac{S}{Nk_B}$  as a function of energy  $\Lambda$  in d=3.

metastable states [61]. Metastable states are important because they can be long lived in systems with long-range interaction [62,63]. The caloric curves may differ in CE and MCE in case of ensembles inequivalence. They are described below in different dimensions of space.

*Remark.* In order to determine the stable branch, we shall compare the entropy (in MCE) or the free energy (in CE) of the different solutions in competition (with the same values of energy or temperature). However, this is not sufficient because a distribution could have a high entropy and be an unstable saddle point. A more rigorous study should therefore investigate the sign of the second-order variations of entropy or free energy for each critical point. But this is a difficult task that is left for future works. In order to find the stable states, we shall use physical considerations, advocate the Poincaré theorem, and exploit results obtained in related studies.

#### 1. Dimension d=1

In Fig. 16 we plot the series of equilibria in d=1. Let us first describe the CE. The control parameter is the inverse temperature  $\eta$  and the stable states are maxima of free en-



FIG. 16. Series of equilibria in d=1. The caloric curve displays a second-order phase transition in CE and MCE taking place at  $\eta = \eta_c^*$  and  $\Lambda = \Lambda_c^*$  (corresponding to  $\lambda = 1$ ). It is marked by the discontinuity of  $\partial \beta / \partial E$  in MCE or  $\partial E / \partial \beta$  in CE. Note that the branches  $\lambda < 1$  and  $\lambda > 1$  coincide. The corresponding density profiles are plotted in Fig. 17.



FIG. 17. Density profiles of the two stable inhomogeneous solutions  $\lambda_1 = 0.69 < 1$  and  $\lambda_2 = 1.54 > 1$  corresponding to  $\eta = 10$  in *d* = 1. We have also represented the unstable homogeneous solution.

ergy J at fixed mass M. The homogeneous phase exists for any value of  $\eta$ . It is fully stable for  $\eta < \eta_c^*$  and unstable for  $\eta > \eta_c^*$  (see Sec. V). The first branch n=1 of inhomogeneous states exists only for  $\eta > \eta_c^*$ . It has a higher free energy J than the homogeneous phase (see Fig. 9) and it is fully stable. Secondary branches of inhomogeneous states appear for smaller values of the temperature but they have smaller values of free energy J (see Fig. 9) and they are unstable (saddle points of free energy). Therefore, the canonical caloric curve displays a second-order phase transition between homogeneous and inhomogeneous states marked by the discontinuity of  $\frac{\partial E}{\partial \beta}$  at  $\beta = \beta_c^*$ . For the inhomogeneous states, there exists two solutions with the same temperature and the same free energy but with different density profiles corresponding to  $\lambda_1 < 1$  and  $\lambda_2 > 1$  (see Fig. 17). Thus, the inhomogeneous branch is degenerate. These two states can be distinguished by their central density  $1/\lambda$ . In conclusion, (i) for  $\eta < \eta_c^*$ , there is only one stable state  $\lambda = 1$  (homogeneous), and (ii) for  $\eta > \eta_c^*$ , there are two stable states  $\lambda_1$ <1 and  $\lambda_2 > 1$  (inhomogeneous) with the same free energy and one unstable state  $\lambda = 1$  (homogeneous). Therefore, the central density  $1/\lambda$  plays the role of an order parameter (see Fig. 3). In d=1, there exists a fully stable equilibrium state for any temperature. This is consistent with the usual Newtonian model in d=1 [20,29]. This is also consistent with results of chemotaxis since it has been rigorously proven that the Keller-Segel model does not blow up in d=1 [8].

Let us now describe the MCE. The control parameter is the energy  $\Lambda$  and the stable states are maxima of entropy *S* at fixed mass *M* and energy *E*. The homogeneous phase exists for any value of energy  $\Lambda < 0$ . It is fully stable for  $\Lambda < \Lambda_c^*$ and unstable for  $\Lambda > \Lambda_c^*$  (see Sec. V). The first branch n=1of inhomogeneous states exists only for  $\Lambda_c^* < \Lambda < \Lambda_{max}$ . It has a higher entropy *S* than the homogeneous phase (see Fig. 12) and it is fully stable. Secondary branches of inhomogeneous states appear for smaller values of the energy but they have smaller values of entropy *S* (see Fig. 12) and they are unstable (saddle points of entropy). Therefore, the microcanonical caloric curve displays a second-order phase transition marked by the discontinuity of  $\frac{\partial \beta}{\partial E}$  at  $E = E_c^*$ . For the inhomogeneous states, there exists two solutions with the



FIG. 18. Series of equilibria in d=2. The first inhomogeneous branch n=1 tends to a plateau  $\eta_c=4$  for large central densities  $1/\lambda \rightarrow +\infty$  due to the formation of a Dirac peak at r=0. This is similar to the plateau appearing in the caloric curve of the classical self-gravitating gas [29].

same energy and the same entropy but with different density profiles corresponding to  $\lambda_1 < 1$  and  $\lambda_2 > 1$ . Thus, the inhomogeneous branch is degenerate. These two states can be distinguished by their central density  $1/\lambda$ . In conclusion, (i) for  $\Lambda < \Lambda_c^*$ , there is only one stable state  $\lambda = 1$  (homogeneous), and (ii) for  $\Lambda_c^* < \Lambda < 0$ , there are two stable states  $\lambda_1 < 1$  and  $\lambda_2 > 1$  (inhomogeneous) with the same entropy and one unstable state  $\lambda = 1$  (homogeneous). (iii) for  $0 < \Lambda < \Lambda_{max}$ , there are two stable states  $\lambda_1 < 1$  and  $\lambda_2 > 1$  (inhomogeneous) with the same entropy. Therefore, the central density  $1/\lambda$  plays the role of an order parameter (see Fig. 6). In d=1, there exists a fully stable equilibrium state for any accessible energy. This is consistent with the usual Newtonian model in d=1 [20,29].

The caloric curve, corresponding to the fully stable states in the series of equilibria, is denoted by (S) in Fig. 16. The branch (U) corresponds to unstable states. There exists a fully stable equilibrium state for any accessible values of energy in MCE and temperature in CE. The microcanonical and canonical ensembles are equivalent (like in the Newtonian case).

In conclusion, the system displays second-order phase transition in CE and MCE. This is similar to the HMF model [33–35].

#### 2. Dimension d=2

In Fig. 18 we plot the series of equilibria in d=2. Let us first describe the CE. The control parameter is the inverse temperature  $\eta$ . The homogeneous phase exists for any  $\eta$ . It is stable for  $\eta < \eta_c^*$  and unstable for  $\eta > \eta_c^*$  (see Sec. V). The first branch n=1 of inhomogeneous states exists for  $\eta > \eta_c$  =4 and it connects the homogeneous branch at  $\eta_c^*$ . For  $\eta < \eta_c^*$ , it has a lower free energy J than the homogeneous phase (see Fig. 10) and it is unstable (it has negative specific heats which is not allowed in the canonical ensemble). For  $\eta > \eta_c^*$ , it has a higher free energy J than the homogeneous phase (see Fig. 10). However, it is expected to be unstable or, possibly, metastable (to settle this issue we have to study the sign of the second-order variations of free energy as ex-



FIG. 19. Caloric curve in the canonical ensemble in d=2. The homogeneous branch is fully stable for  $\eta < \eta_c=4$ , metastable for  $\eta_c < \eta < \eta_c^*$  and unstable for  $\eta > \eta_c^*$ . The inhomogeneous branch is always unstable (or, possibly, metastable for  $\eta > \eta_c^*$ ). For sufficiently low temperatures, the system can experience an isothermal collapse.

plained above). Secondary inhomogeneous branches appear for smaller values of the temperature but they have smaller values of the free energy (see Fig. 10) and they are unstable. The homogeneous branch is expected to be fully stable for  $\eta < \eta_c = 4$  and metastable for  $\eta_c = 4 < \eta < \eta_c^*$  (see Fig. 19). These conclusions are motivated by two arguments. (i) In the Newtonian model in d=2, we know that there exists a fully stable equilibrium state for  $\eta < \eta_c = 4$  and no equilibrium state for  $\eta > \eta_c = 4$ . In that case, the system undergoes an *isothermal collapse* [19,29]. For  $\eta > \eta_c = 4$ , there is no global maximum of free energy J because we can make it diverge by creating a Dirac peak containing all the particles. In the modified Newtonian model, the same argument applies since it is independent of boundary conditions. Since we know that the homogeneous branch is stable for  $\eta < \eta_c^*$ , we conclude that it must be metastable in the range  $\eta_c = 4 < \eta < \eta_c^*$ . Considering only fully stable states, there is therefore a zerothorder phase transition at  $\eta_c=4$  marked by the discontinuity of the free energy. (ii) In the chemotactic literature, it has been rigorously established that the Keller-Segel model in d=2 does not blow up for  $\eta < \eta_c = 4$  while it can blow up for  $\eta > \eta_c = 4$  [8]. This is consistent with our stability results.

Let us now describe the MCE. The control parameter is the energy  $\Lambda$ . The homogeneous phase exists for all values of  $\Lambda < 0$ . It is stable for  $\Lambda < \Lambda^*$  and unstable for  $\Lambda > \Lambda^*$  (see Sec. V). The first branch n=1 of inhomogeneous states exists for  $\Lambda > \Lambda_*$  (see Fig. 20) and it connects the homogeneous branch at  $\Lambda_c^*$ . We see that the inhomogeneous branch  $\beta(E)$ can be multivalued. Considering the value of the entropy in the different phases (see Figs. 13 and 14), the caloric curve is expected to display a microcanonical first-order phase transition at  $\Lambda = \Lambda_t \approx -0.146$  marked by the discontinuity of the temperature (see Fig. 20). The energy of transition has been determined by comparing the entropy of the homogeneous and inhomogeneous phases and looking at which point the curves S(E) intersect (see Fig. 14). Equivalently, it can be obtained by performing a vertical Maxwell construction [32]. The homogeneous phase is fully stable for  $\Lambda < \Lambda_t$ , metastable for  $\Lambda_t < \Lambda < \Lambda_c^*$ , and unstable for  $\Lambda > \Lambda_c^*$ . The lower



FIG. 20. Caloric curve in the microcanonical ensemble in d=2. Note that the lower branch has negative specific heats. A first-order phase transition is expected to take place in the microcanonical ensemble at  $\Lambda = \Lambda_t$ . However, this phase transition may not take place in practice because metastable states can have very long life-times for systems with long-range interaction.  $\Lambda_*$  and possibly  $\Lambda_c^*$  represent microcanonical spinodal points marking the end of the metastable phase.

part of the first inhomogeneous branch is fully stable for  $\Lambda > \Lambda_t$  and metastable for  $\Lambda_* < \Lambda < \Lambda_t$ . The upper part of the first inhomogeneous branch is unstable for  $\Lambda_* < \Lambda < \Lambda_c^*$ . For  $\Lambda > \Lambda_c^*$ , it is unstable or, possibly, metastable. Secondary inhomogeneous branches appear for smaller values of the energy but they have smaller values of the entropy (see Fig. 13) and they are unstable. The stable states of the inhomogeneous branch have  $1/\lambda > 1$  indicating that the density is concentrated at the center. The possibly metastable states for  $\Lambda > \Lambda_c^*$  have  $1/\lambda < 1$  indicating that the density is concentrated near the box. In conclusion, there exists a fully stable equilibrium state for any value of energy. This is similar to the Newtonian model in d=2 [24,29]. However, in the modified Newtonian model, we expect a first-order phase transition at  $\Lambda_t$  that is not present in the Newtonian model.

The strict caloric curve, corresponding to the fully stable states (global maxima) in the series of equilibria, is denoted (S) in Figs. 19 and 20. The unstable states (saddle points) are denoted (U) and the metastable states (local maxima) are denoted (M). There exists a fully stable equilibrium state for any accessible value of energy in MCE and for sufficiently high values of the temperature in CE ( $\eta < \eta_c = 4$ ). Here, the microcanonical and canonical ensembles are inequivalent (unlike in the Newtonian case). In particular, the lower part of the first inhomogeneous branch is stable in MCE while it is unstable in CE. This branch has negative specific heats C < 0 (see Fig. 20) which is not possible in the canonical ensemble.

In conclusion, the system displays a zeroth order phase transition in CE (associated with an isothermal collapse) and a first-order phase transition in MCE. Note also that the energy  $E(\beta)$  and its first derivative  $E'(\beta)$  are continuous at the critical point  $\beta_c^*$  but its second derivative  $E''(\beta)$  is discontinuous. Provided that the inhomogeneous branch for  $\eta > \eta_c^*$  is metastable, this would correspond to a third-order



FIG. 21. Series of equilibria in d=3. The inhomogeneous branch forms a spiral for large central densities  $1/\lambda \rightarrow +\infty$  due to the damped oscillations of the inverse temperature  $\eta(\lambda)$  and energy  $\Lambda(\lambda)$ . This is similar to the spiral appearing in the series of equilibria of the classical self-gravitating gas as we approach the singular isothermal sphere [29].

canonical phase transition between a homogeneous metastable state and an inhomogeneous metastable state.

#### 3. Dimension d=3

In Fig. 21 we plot the series of equilibria in d=3. Let us first describe the CE. The control parameter is  $\eta$ . The homogeneous phase exists for all  $\eta$ . It is stable for  $\eta < \eta_c^*$  and unstable for  $\eta > \eta_c^*$  (see Sec. V). The first branch n=1 of inhomogeneous states exists for  $\eta > 2.64$  and it connects the homogeneous branch at  $\eta = \eta_{a}^{*}$ . For large central densities  $1/\lambda$ , it forms a spiral toward a singular solution. For  $\eta$  $< \eta_c^*$ , it has a lower free energy J than the homogeneous phase (see Fig. 11) and it is unstable. For  $\eta > \eta_c^*$ , it has a higher free energy J than the homogeneous phase (see Fig. 11). However, it is expected to be unstable or, possibly, metastable. Secondary inhomogeneous branches appear for smaller values of the temperature but they have a lower value of free energy J and they are unstable. The homogeneous branch is metastable for  $\eta < \eta_c^*$ . These conclusions are motivated by two arguments. (i) In the Newtonian model in d=3, we know that there is no fully stable equilibrium state in CE. The system can undergo an *isothermal collapse* [27,29]. There is no global maximum of free energy J because we can make it diverge by creating a Dirac peak containing all the particles [21,27,29]. In the modified Newtonian model, the same argument applies since it is independent on boundary conditions. Since we know that the homogeneous branch is stable for  $\eta < \eta_c^*$ , then it can only be metastable. (ii) In the chemotactic literature, it has been rigorously established that the Keller-Segel model in d=3 can blow up for any  $\eta$  [8]. This is consistent with our stability results.

Let us now describe the MCE. The control parameter is the energy  $\Lambda$ . The homogeneous phase exists for all  $\Lambda < 0$ . It is stable for  $\Lambda < \Lambda_c^*$  and unstable for  $\Lambda > \Lambda_c^*$  (see Sec. V). The first branch n=1 of inhomogeneous states exists for  $\Lambda$ >-0.405 and it connects the homogeneous branch at  $\Lambda$  $= \Lambda_c^*$ . For large central densities  $1/\lambda$ , it forms a spiral towards a singular solution. For  $\Lambda < \Lambda_c^*$ , it has a lower entropy S than the homogeneous phase (see Fig. 15) and it is unstable. For  $\Lambda > \Lambda_c^*$ , it has a higher entropy than the homogeneous phase (see Fig. 15). However, it is expected to be unstable or, possibly, metastable. Secondary inhomogeneous branches appear for smaller values of the energy but they have a lower value of entropy S and they are unstable. The homogeneous branch is metastable for  $\Lambda < \Lambda^*$ . These conclusions are motivated by two arguments. (i) In the Newtonian model in d=3, we know that there is no fully stable equilibrium state in MCE. The system undergoes a gravothermal catastrophe [13,14]. There is no global maximum of entropy S at fixed mass and energy because we can make it diverge by creating a binary star surrounded by a hot halo [22,29,32]. In the modified Newtonian model, the same argument applies. Since we know that the homogeneous branch is stable for  $\Lambda < \Lambda^*$ , then it can only be metastable.

There is no strict caloric curve since there are no fully stable states (global maxima). But there is a physical caloric curve made of metastable states (local maxima) denoted (M) in Fig. 21. The unstable states (saddle points) are denoted (U). Here, the microcanonical and canonical ensembles, regarding the metastable states, are equivalent unlike in the Newtonian case. This is because the homogeneous branch and the inhomogeneous branch connect each other at a *single* point at  $\lambda = 1$  by making a cusp (see inset in Fig. 21) while the Newtonian series of equilibria is smooth and presents *two* distinct turning points of temperature and energy (denoted CE and MCE in Fig. 8 of [32]) separated by a region of negative specific heats.

In conclusion, if we take metastable states into account, the system displays a zeroth order phase transition in CE and MCE corresponding to a discontinuity of entropy or free energy. They are associated with an isothermal collapse or a gravothermal catastrophe, respectively.

*Remark.* There is no natural external parameter in the modified Newtonian model. However, the dimension of space d could play the role of an effective external parameter. The preceding results predict the existence of a critical dimension  $d_c$  between 1 and 2 at which the microcanonical phase transition passes from second order (d=1) to first order (d=2). However, this transition turns out to occur in a very small range of parameters since we find that the critical dimension  $d_c$  is between 1 and d=1.00001 and the concerned range of energies and temperatures is extremely narrow. We have not investigated this transition in detail since the dimension of space is not a physical (tunable) parameter. Furthermore, in the next model, we have an external parameter  $\mu$  played by screening length that is more physically relevant.

## **IV. SCREENED NEWTONIAN MODEL**

In this section, we discuss phase transitions that appear in the screened Newtonian model corresponding to an attractive Yukawa potential.

#### A. Physical motivation of the model

We consider a system of particles interacting via the potential  $\Phi(\mathbf{r}, t)$  that is solution of the screened Poisson equation

$$\Delta \Phi - k_0^2 \Phi = S_d G \rho, \tag{65}$$

where  $k_0$  is the inverse of the screening length. At statistical equilibrium, the density is given by the Boltzmann distribution

$$\rho = A e^{-\beta m \Phi}.$$
 (66)

We assume that the system is confined in a finite domain (box) and we impose the Neumann boundary conditions

$$\nabla \Phi \cdot \mathbf{n} = 0, \quad \nabla \rho \cdot \mathbf{n} = 0, \tag{67}$$

where **n** is a unit vector normal to the boundary of the box (the explicit expression of the potential in d=1 is given in Appendix B). This model admits spatially homogeneous solutions ( $\rho = \rho_0$  and  $\Phi = \Phi_0$  with  $-k_0^2 \Phi_0 = S_d G \rho_0$ ) at any temperature. It also admits spatially inhomogeneous solutions at sufficiently low temperatures. We shall study this model in arbitrary dimensions of space *d* with explicit computations for d=1,2,3. This model has different physical applications.

(i) It describes a system of particles interacting via a screened attractive (Newtonian) potential. In fact, the field equation (65) was first introduced by Einstein [64] (and previously by Seeliger in 1895) in order to obtain an infinite homogeneous static universe. In Einstein's belief, the shielding factor  $k_0^2$  was the Newtonian analog of the cosmological constant  $\kappa^2 = 8\pi G\Lambda$ . For other authors such as Lemaître [65] and Eddington [66], the Newtonian analog of the cosmological constant is a repulsive force leading to a Poisson equation of the form  $\Delta \Phi = 4\pi G\rho - \kappa^2 = 4\pi G(\rho - 2\Lambda)$ , allowing also an infinite homogeneous static universe. We refer to Spiegel [67] and Kiessling [68] for further details on these interesting historical issues.

(ii) By a proper reinterpretation of the parameters, the field equation (65) describes the relation between the concentration of the chemical and the density of bacteria in the Keller-Segel model (32)–(38) where the degradation of the chemical reduces the range of the interaction. In that case, the boundary conditions are of form (67). Furthermore, the relevant ensemble is the CE since the KS model has a canonical structure. This model has been studied by Childress and Percus [69] in d=1 using an approach different from the one we are going to develop. For the sake of generality, we shall study this model in the microcanonical and canonical ensembles in any dimension of space.

#### **B.** Screened Emden equation

In the screened Newtonian model, the equilibrium density profile is given by the Boltzmann distribution (66) coupled to the screened Poisson equation (65). As in Sec. III B, we look for spherically symmetric solutions. Introducing the central density  $\rho_0 = \rho(0)$ , the central potential  $\Phi_0 = \Phi(0)$ , the new field  $\psi = \beta m (\Phi - \Phi_0)$ , and the scaled distance  $\xi$  $= (S_d G \beta m \rho_0)^{1/2} r$ , the Boltzmann distribution can be rewritten as

$$\rho = \rho_0 e^{-\psi(\xi)}.\tag{68}$$

Substituting this relation in the screened Poisson equation (65), we obtain the screened Emden equation



FIG. 22. Inverse temperature  $\eta$  as a function of  $\alpha$  for the first two branches in d=1. We have taken  $\mu=1 < \mu_c$ .

$$\frac{1}{\xi^{d-1}}\frac{d}{d\xi}\left(\xi^{d-1}\frac{d\psi}{d\xi}\right) - \kappa^2\psi = e^{-\psi} - \lambda, \tag{69}$$

where  $\kappa = k_0 / (S_d G \beta m \rho_0)^{1/2}$  and  $\lambda = -k_0^2 \Phi_0 / S_d G \rho_0$ . The boundary conditions at the origin are

$$\psi(0) = \psi'(0) = 0. \tag{70}$$

The normalized box radius is  $\alpha = (S_d G\beta m\rho_0)^{1/2}R$  and the boundary condition  $\Phi'(R) = 0$  becomes

$$\psi'(\alpha) = 0. \tag{71}$$

Introducing the normalized screening length

$$\mu = k_0 R, \tag{72}$$

the parameter  $\kappa$  can be rewritten as  $\kappa = \mu/\alpha$ . For given  $\mu$ , we solve the problem as follows. (i) We fix  $\alpha$ . (ii)  $\kappa = \mu/\alpha$  is then given. (iii) We determine  $\lambda$  by an iterative method such that  $\psi'(\alpha)=0$ . (iv) We obtain different solutions  $\lambda_n(\alpha)$  determining different branches n=1, n=2, etc. This procedure determines for each value of  $\alpha$ , and for each branch, the normalized density profile  $e^{-\psi(\xi)}$ . The homogeneous solution corresponds to  $\psi=0$  and  $\lambda=1$ . This solution is degenerate because the boundary condition (71) is satisfied for any value of  $\alpha$ .



FIG. 23. Inverse temperature  $\eta$  as a function of  $\alpha$  for the first two branches in d=1. We have taken  $\mu=10 > \mu_c$ .



FIG. 24. Inverse temperature  $\eta$  as a function of  $\alpha$  for the first two branches in d=2. For  $\alpha \rightarrow +\infty$ , the inverse temperature of the first branch tends to  $\eta_c=4$ . We have taken  $\mu=1$ .

## C. Temperature

We must now relate the parameter  $\alpha$  to the temperature *T*. Introducing the dimensionless variables defined previously and recalling that  $r=R\xi/\alpha$ , the mass can be written as

$$M = \rho_0 S_d \left(\frac{R}{\alpha}\right)^d \int_0^\alpha e^{-\psi} \xi^{d-1} d\xi.$$
(73)

Using  $\alpha = (S_d G \beta m \rho_0)^{1/2} R$  and introducing the dimensionless inverse temperature (52), we obtain

$$\eta = \frac{1}{\alpha^{d-2}} \int_0^\alpha e^{-\psi} \xi^{d-1} d\xi.$$
 (74)

This equation gives the relation between the inverse temperature  $\eta$  and  $\alpha$  for the *n*th branch. In Figs. 22–25, we plot the inverse temperature  $\eta$  as a function of  $\alpha$  for the first two branches n=1,2 in different dimensions of space d=1,2,3. The discussion is similar to the one given in Sec. III C. We have also represented the branch corresponding to the homogeneous solution. Its equation is given by  $\eta = \alpha^2/d$ . The branch n=1 of inhomogeneous solutions connects the branch of homogeneous solutions at  $\alpha_c^2 = d \eta_c^*$  (see Appendix F).



FIG. 25. Inverse temperature  $\eta$  as a function of  $\alpha$  for the first two branches in d=3. For  $\alpha \rightarrow +\infty$ , the inverse temperature of the first branch undergoes damped oscillations around the value  $\eta_s \approx 3.25$ . We have taken  $\mu=1$ .



FIG. 26. Energy  $\Lambda$  as a function of  $\alpha$  for the first two branches in d=1. We have taken  $\mu=1 < \mu_c$ .

# **D.** Energy

We must also relate  $\alpha$  to the energy *E*. The total energy is given by

$$E = \int f \frac{v^2}{2} d\mathbf{r} d\mathbf{v} + \frac{1}{2} \int \rho \Phi d\mathbf{r}.$$
 (75)

Using the Maxwell-Boltzmann distribution (10), the kinetic energy is simply

$$K = \frac{d}{2}Nk_BT.$$
 (76)

Using the screened Poisson equation (65) and integrating by parts, the potential energy can be written as

$$W = -\frac{1}{2S_d G} \int \left[ (\nabla \Phi)^2 + k_0^2 \Phi^2 \right] d\mathbf{r}.$$
 (77)

The total energy E = K + W is therefore given by

$$E = \frac{d}{2}Nk_BT - \frac{1}{2S_dG}\int \left[ (\nabla\Phi)^2 + k_0^2 \Phi^2 \right] d\mathbf{r}.$$
 (78)

Introducing the dimensionless variables defined previously, recalling that  $r = \xi R / \alpha$  and  $\mu = k_0 R$ , and introducing the normalized energy (58), we obtain

$$\Lambda = -\frac{d}{2\eta} + \frac{1}{2\eta^2} \frac{1}{\alpha^{d-2}} \int_0^\alpha \left(\frac{d\psi}{d\xi}\right)^2 \xi^{d-1} d\xi + \frac{\mu^2}{2\eta^2} \frac{1}{\alpha^d} \int_0^\alpha (\psi + \beta m \Phi_0)^2 \xi^{d-1} d\xi.$$
(79)

Using the expressions of  $\kappa$  and  $\lambda$  following Eq. (69), we find that

$$\beta m \Phi_0 = -\frac{\lambda}{\kappa^2},\tag{80}$$

so that, finally,



FIG. 27. Energy  $\Lambda$  as a function of  $\alpha$  for the first two branches in d=1. We have taken  $\mu_m > \mu = 10 > \mu_c$ .

$$\Lambda = -\frac{d}{2\eta} + \frac{1}{2\eta^2} \frac{1}{\alpha^{d-2}} \int_0^\alpha \left(\frac{d\psi}{d\xi}\right)^2 \xi^{d-1} d\xi + \frac{\mu^2}{2\eta^2} \frac{1}{\alpha^d} \int_0^\alpha \left(\psi - \frac{\lambda \alpha^2}{\mu^2}\right)^2 \xi^{d-1} d\xi.$$
(81)

This equation gives the relation between the energy  $\Lambda$  and  $\alpha$  for the *n*th branch. In Figs. 26–30, we plot the energy  $\Lambda$  as a function of  $\alpha$  for the first two branches n=1 and n=2 in different dimensions of space d=1,2,3. The discussion is similar to the one given in Sec. III D. We have also represented the branch corresponding to the homogeneous solution. Using Eq. (88) and  $\eta = \alpha^2/d$ , its equation is given by  $\Lambda = -d^2/(2\alpha^2) + d/(2\mu^2)$ .

#### E. Entropy and free energy

Finally, we relate  $\alpha$  to the entropy *S* and to the free energy *F*. The entropy is given by

$$S = \frac{d}{2}Nk_B \ln T - k_B \int \frac{\rho}{m} \ln \frac{\rho}{m} d\mathbf{r}.$$
 (82)

We can proceed exactly as in Sec. III E and obtain



FIG. 28. Energy  $\Lambda$  as a function of  $\alpha$  for the first two branches in d=1. We have taken  $\mu=15 > \mu_m$ .



FIG. 29. Energy  $\Lambda$  as a function of  $\alpha$  for the first two branches in d=2. We have taken  $\mu=1$ .

$$\frac{S}{Nk_B} = -\frac{d-2}{2} \ln \eta - 2 \ln \alpha + \frac{1}{\eta} \frac{1}{\alpha^{d-2}} \int_0^\alpha \psi e^{-\psi} \xi^{d-1} d\xi$$
(83)

up to unimportant constants. However, we can also obtain a simpler expression. Substituting  $\rho = \rho_0 e^{-\beta m (\Phi - \Phi_0)}$  in Eq. (82), we obtain

$$S = \frac{d}{2}Nk_B \ln T - k_B \int \frac{\rho}{m} \ln \frac{\rho_0}{m} d\mathbf{r} + k_B \beta \int \rho(\Phi - \Phi_0) d\mathbf{r}.$$
(84)

This can be rewritten as

$$\frac{S}{Nk_B} = -\frac{d}{2}\ln\beta - \ln\rho_0 + \frac{2\beta E}{N} - \beta m\Phi_0$$
(85)

up to unimportant constants. Finally, using Eqs. (80), (52), and (58) and the relations  $\kappa = \mu/\alpha$  and  $\alpha = (S_d G \beta m \rho_0)^{1/2} R$ , we obtain



FIG. 30. Energy  $\Lambda$  as a function of  $\alpha$  for the first two branches in d=3. For  $\alpha \rightarrow +\infty$ , the energy of the first branch undergoes damped oscillations around the value  $\Lambda_s \simeq 1.13$ . We have taken  $\mu = 1$ .



FIG. 31. Free energy  $\frac{J}{Nk_B}$  as a function of the inverse temperature  $\eta$  for d=1. We have taken  $\mu=1 < \mu_c$ .

$$\frac{S}{Nk_B} = -\frac{d-2}{2} \ln \eta - 2 \ln \alpha - 2\Lambda \eta + \frac{\lambda \alpha^2}{\mu^2}, \qquad (86)$$

which does not involve new integrals. Using the previous results, this expression relates the entropy  $S/Nk_B$  to  $\alpha$ . The free energy is F=E-TS. In the following, it will be more convenient to work in terms of the Massieu function J=S  $-k_B\beta E$  (by an abuse of language, we shall often refer to J as the free energy). We have

$$\frac{J}{Nk_B} = \frac{S}{Nk_B} + \eta \Lambda.$$
(87)

Using the previous results, this expression relates the free energy  $J/Nk_B$  to  $\alpha$ .

In Figs. 31–34, we have plotted the free energy  $J/Nk_B$  as a function of the inverse temperature  $\eta$  (parametrized by  $\alpha$ ) in d=1,2,3. In Figs. 35–38, we have plotted the entropy  $S/Nk_B$  as a function of the energy  $\Lambda$  (parametrized by  $\alpha$ ) in d=1,2,3.



FIG. 32. Free energy  $\frac{J}{Nk_B}$  as a function of the inverse temperature  $\eta$  for d=1. We have taken  $\mu=10 > \mu_c$ . The free energies of the homogeneous phase and inhomogeneous phase become equal at  $\eta = \eta_l(\mu)$ . This corresponds to a first order phase transition in the canonical ensemble marked by the discontinuity of the slope  $J'(\beta) = -E$ .



FIG. 33. Free energy  $\frac{J}{Nk_B}$  as a function of the inverse temperature  $\eta$  for d=2. We have taken  $\mu=1$ .

#### F. Caloric curve

We shall now determine the caloric curve  $\beta(E)$  corresponding to the screened Newtonian model. First of all, we note that, for the homogeneous phase, we have  $\rho = \rho_0$  and  $\Phi = \Phi_0$  with  $-k_0^2 \Phi_0 = S_d G \rho_0$  (or equivalently  $\psi = 0$ ,  $\lambda = 1$  and  $\alpha^2 = d \eta$ ). Therefore, the relationship between the energy and the temperature can be written as

$$\Lambda = -\frac{d}{2\eta} + \frac{d}{2\mu^2}.$$
(88)

This shows that  $\eta \rightarrow +\infty$  for  $\Lambda \rightarrow \Lambda_{\max} = d/(2\mu^2)$ . On the other hand, eliminating  $\alpha$  between  $\eta_n(\alpha)$  and  $\Lambda_n(\alpha)$  given by Eqs. (74) and (81), we get the series of equilibria for the *n*th inhomogeneous branch. The series of equilibria (critical points) and the caloric curves (stable states) in CE and MCE are described below for different dimensions of space.

#### 1. Dimension d=1

In Figs. 39 and 40, we plot the series of equilibria in d = 1 for different values of the screening parameter  $\mu$ .

Let us first describe the CE. The control parameter is the inverse temperature  $\eta$  and the stable states are maxima of free energy *J* at fixed mass *M*. The homogeneous phase exists for any value of  $\eta$ . It is stable for  $\eta < \eta_c^*$  and unstable for



FIG. 34. Free energy  $\frac{J}{Nk_{B}}$  as a function of the inverse temperature  $\eta$  for d=3. We have taken  $\mu=1$ .



FIG. 35. Entropy  $\frac{S}{Nk_B}$  as a function of the energy  $\Lambda$  for d=1. We have taken  $\mu=1 < \mu_c$ .

 $\eta > \eta_c^*$  (see Sec. V). Comparing Figs. 39 and 40, we see that the screened Newtonian model is characterized by a pitchfork bifurcation at  $\eta = \eta_c^*$ . The pitchfork bifurcation is supercritical if  $\mu < \mu_c = \sqrt{2\pi} \approx 4.442\,882\,9$  and subcritical if  $\mu > \mu_c$ . This interesting transition was first evidenced by Childress and Percus [69] using a different approach. In our thermodynamical approach, this implies the existence of a canonical tricritical point at  $\mu_c = \sqrt{2\pi}$ . For  $\mu < \mu_c$  the phase transition is second order and for  $\mu > \mu_c$  the phase transition is first order.

Let us first consider  $\mu < \mu_c$  (see Fig. 39). The discussion is similar to that given for the modified Newtonian model. The first branch n=1 of inhomogeneous states exists only for  $\eta > \eta_c^*$ . It has a higher free energy *J* than the homogeneous phase (see Fig. 31) and it is fully stable. Secondary branches appear for smaller values of the temperature but they have smaller values of free energy *J* (see Fig. 31) and they are unstable (saddle points of free energy). Therefore, the canonical caloric curve displays a second order phase transition between homogeneous and inhomogeneous states marked by the discontinuity of  $\frac{\partial E}{\partial \beta}$  at  $\beta = \beta_c^*$ . We note that for the inhomogeneous states, there exists two solutions with the same temperature and the same free energy but with different den-



FIG. 36. Entropy  $\frac{S}{Nk_B}$  as a function of the energy  $\Lambda$  for d=1. We have taken  $\mu_m > \mu = 10 > \mu_c$ . There is a (small) convex dip associated with the region of negative specific heats in the microcanonical ensemble.



FIG. 37. Entropy  $\frac{S}{Nk_B}$  as a function of the energy  $\Lambda$  for d=2. We have taken  $\mu=1$ .

sity profiles corresponding to  $\alpha_1 < \alpha_c$  and  $\alpha_2 > \alpha_c$ , where  $\alpha_c$  is the value of  $\alpha$  at the point of contact with in the homogeneous branch. Thus, the inhomogeneous branch is degenerate. These two states can be distinguished by their central density  $\alpha$ . Since  $\bar{\rho}/\rho_0 = d\eta/\alpha^2$ , the solution  $\alpha_1 < \alpha_c$  corresponds to  $\rho_0 < \bar{\rho}$  and the solution  $\alpha_2 > \alpha_c$  corresponds to  $\rho_0 < \bar{\rho}$ . The density profiles are similar to those represented in Fig. 17 for the modified Newtonian model. In conclusion, (i) for  $\eta < \eta_c^*$ , there is only one stable state (homogeneous) and (ii) for  $\eta > \eta_c^*$ , there are two stable states  $\alpha_1 < \alpha_c$  and  $\alpha_2 > \alpha_c$  (inhomogeneous) with the same free energy and one unstable state (homogeneous). Therefore, the central density  $\alpha$  plays the role of an order parameter (see Fig. 22).

Let us now consider  $\mu > \mu_c$  (see Fig. 40). The first branch n=1 of inhomogeneous states exists only for  $\eta > \eta_*(\mu)$  (see Fig. 41). The caloric curve displays a canonical first order phase transition at  $\eta_t(\mu)$  marked by the discontinuity of the energy *E* (see Fig. 41). The temperature of transition  $\eta_t(\mu)$  can be obtained by plotting the free energy of the two phases as a function of the temperature and determining at which temperature they become equal (see Fig. 32). Equivalently, it can be obtained by performing a horizontal Maxwell construction [32]. The homogeneous phase is fully stable for  $\eta < \eta_t$ , metastable for  $\eta_t < \eta < \eta_c^*$  and unstable for  $\eta > \eta_c^*$ . The right branch of the inhomogeneous phase is fully stable for  $\eta > \eta_t$  and metastable for  $\eta_* < \eta < \eta_t$ . The left branch is un-



FIG. 38. Entropy  $\frac{S}{Nk_B}$  as a function of the energy  $\Lambda$  for d=3. We have taken  $\mu=1$ .



FIG. 39. Series of equilibria in d=1 for  $\mu=1 < \mu_c$ . The caloric curve displays a second-order phase transition in CE and MCE taking place at  $\eta = \eta_c^*$  and  $\Lambda = \Lambda_c^*$ . It is marked by the discontinuity of  $\partial E / \partial \beta$  in CE or  $\partial \beta / \partial E$  in MCE. Note that the branches  $\alpha < \alpha_c$  and  $\alpha > \alpha_c$  coincide. For  $\mu < \mu_c$ , the CE and MCE ensembles are equivalent.

stable. Note that this branch has negative specific heats which is not permitted in the canonical ensemble. Secondary branches appear for smaller values of the temperature but they have smaller values of free energy J and they are unstable. We also note that the branch of inhomogeneous states is degenerate since the curves  $\alpha < \alpha_c$  and  $\alpha > \alpha_c$  coincide. In conclusion, (i) for  $\eta < \eta_*$ , there is only one stable state (homogeneous), (ii) for  $\eta_* < \eta < \eta_c^*$ , there are three stable states (one homogeneous and two inhomogeneous) and two unstable states (inhomogeneous) and (iii) for  $\eta > \eta_c^*$ , there are two stable states (inhomogeneous) and one unstable state (homogeneous). The pairs of inhomogeneous states have the same free energy. Therefore, the central density  $\alpha$  plays the role of an order parameter (see Fig. 23).

The canonical phase diagram is represented in Fig. 42 where we have plotted  $\eta_c^*$ ,  $\eta_*$ , and  $\eta_t$  as a function of  $\mu$ . The three temperatures coincide at the tricritical point  $\mu = \mu_c$ . At that point, the phase transition goes from second order ( $\mu < \mu_c$ ) to first order ( $\mu > \mu_c$ ).

The strict caloric curve (see Figs. 39 and 41), corresponding to the fully stable states, is denoted (S). The physical caloric curve should take into account the metastable states (M) because they are long lived. The states (U) are unstable.



FIG. 40. Series of equilibria in d=1 for  $\mu=10>\mu_c$ .



FIG. 41. Canonical caloric curve in d=1 for  $\mu=10>\mu_c$ . It displays a canonical first-order phase transition marked by the discontinuity of the energy at  $\eta=\eta_t(\mu)$ . The region of negative specific heats is unstable in the canonical ensemble and replaced by a phase transition (Maxwell plateau). The temperatures  $\eta_c^*$  and  $\eta_*$  represent canonical spinodal points marking the end of the metastable phase.

We see that there exists a fully stable equilibrium state for any temperature and any screening length. This is consistent with the usual Newtonian model in d=1 [20,29]. This is also consistent with the results of chemotaxis since it has been established rigorously that there is no blow up in d=1 [8].

Let us finally describe the MCE. The control parameter is the energy  $\Lambda$  and the stable states are maxima of entropy *S* at fixed mass *M* and energy *E*. The homogeneous phase exists for any  $\Lambda < \Lambda_{max} = d/(2\mu^2)$ . It is stable for  $\Lambda < \Lambda_c^*$  and unstable for  $\Lambda > \Lambda_c^*$  (see Sec. V). Comparing Figs. 43 and 44, we see that there exists a microcanonical tricritical point at  $\mu_m \approx 11.8$  and  $\Lambda \approx 2.37 \times 10^{-4}$  (corresponding to  $\eta$  $\approx 149.1096$ ). For  $\mu < \mu_m$  the phase transition is second order and for  $\mu > \mu_m$  the phase transition is first order.

Let us first consider  $\mu < \mu_m$  (see Figs. 39 and 43). The first branch n=1 of inhomogeneous states exists for  $\Lambda_c^* < \Lambda < \Lambda_{max}^{(1)} = 1/[2\mu \tanh(\mu)]$  (see Appendix D). It has a higher entropy *S* than the homogeneous phase and it is stable (see Figs. 35 and 36). Secondary branches appear for smaller values of the energy but they have smaller values of entropy and are unstable. The microcanonical caloric curve displays



FIG. 42. Canonical phase diagram in d=1 exhibiting a tricritical point at  $\mu_c = \sqrt{2}\pi \approx 4.44$  and  $\eta \approx 29.6$ . We have represented  $\eta_c^*$ ,  $\eta_*$ , and  $\eta_t$  as a function of  $\mu$ . The region between  $\eta_*$  and  $\eta_c^*$  contains stable and metastable states.



FIG. 43. Microcanonical caloric curve in d=1 for  $\mu_m > \mu = 10$ > $\mu_c$ . It displays a microcanonical second order phase transition marked by the discontinuity of  $\frac{\partial \beta}{\partial E}$  at  $E = E_c^*$ . For  $\mu > \mu_c$ , there exists a region of negative specific heats that is stable in the microcanonical ensemble.

a second order phase transition marked by the discontinuity of  $\frac{\partial \beta}{\partial E}$  at  $E = E_c^*$ . For  $\mu < \mu_c$ , the specific heat is always positive. In that case, the microcanonical and canonical ensembles are equivalent. For  $\mu > \mu_c$ , a region of negative specific heats appears. This leads to a convex dip in the entropic curve S(E) (see Fig. 36). In that case, the microcanonical and canonical ensembles are inequivalent: the states with negative specific heats are stable in MCE while they are unstable in CE (compare Figs. 41 and 43). Therefore, these energies cannot be achieved in a canonical description.

Let us now consider  $\mu > \mu_m$  (see Fig. 44). The first branch n=1 of inhomogeneous states exists only for  $\Lambda_{max}^{(1)} > \Lambda > \Lambda_*(\mu)$ . The caloric curve displays a microcanonical first order phase transition at  $\Lambda_t(\mu)$  marked by the discontinuity of the temperature *T* and the existence of metastable states. The energy of transition  $\Lambda_t(\mu)$  can be obtained by plotting the entropy of the two phases as a function of the energy and determining at which energy they become equal (the figure is not represented because the interval where this crossing takes place is very narrow). Equivalently, it can be obtained by



FIG. 44. Microcanonical caloric curve in d=1 for  $\mu=15 > \mu_m$ . It displays a microcanonical first order phase transition marked by the discontinuity of *T* at  $E=E_t$ . The energies  $E_c^*$  and  $E_*$  are spinodal points marking the end of the metastable branches. Note that this first order phase transition occurs in an extremely small range of energies.



FIG. 45. Microcanonical phase diagram in d=1 exhibiting a tricritical point at  $\mu_m \approx 11.8$  and  $\Lambda \approx 2.37 \, 10^{-4}$ . We have represented  $\Lambda_c^*$ ,  $\Lambda_*$  and  $\Lambda_t$  as a function of  $\mu$ . The region between  $\Lambda_*$  and  $\Lambda_c^*$  contains stable and metastable states. We again emphasize the small range of energies where this first order phase transition takes place.

performing a vertical Maxwell construction [32]. The discussion is similar to that given in the canonical ensemble except that the axis are reversed. In conclusion: (i) for  $\Lambda < \Lambda_*$ , there is only one stable state (homogeneous); (ii) for  $\Lambda_* < \Lambda < \Lambda_c^*$ , there are three stable states (one homogeneous and two inhomogeneous) and two unstable states (inhomogeneous), and (iii) for  $\Lambda > \Lambda_c^*$ , there are two stable states (inhomogeneous) and one unstable state (homogeneous). The pairs of inhomogeneous states have the same entropy. Therefore, the central density  $\alpha$  plays the role of an order parameter (see Fig. 28).

The microcanonical phase diagram is represented in Figs. 45 and 46 where we have plotted  $\Lambda_c^*$ ,  $\Lambda_*$ , and  $\Lambda_t$  as a function of  $\mu$ . The three energies coincide at the microcanonical tricritical point  $\mu = \mu_m$ . At that point, the phase transition goes from second order ( $\mu < \mu_m$ ) to first order ( $\mu > \mu_m$ ). We have also represented the region of negative specific heats which appears at the canonical tricritical point  $\mu = \mu_c$ . For



FIG. 46. Microcanonical phase diagram in d=1. We have represented  $\Lambda_c^*$ ,  $\Lambda'$ ,  $\Lambda_1$  and  $\Lambda_2$  as a function of  $\mu$ . These energies coincide for  $\mu_c = \sqrt{2}\pi \approx 4.44$  and  $\Lambda \approx 0.0084$ . These energies delimitate respectively the region of negative specific heats and the region of strict ensembles inequivalence (see main text): the energies in these regions cannot be reached in the canonical ensemble.



FIG. 47. Caloric curve in d=2 for  $\mu=1$ .

 $\mu_c < \mu < \mu_m$ , it is delimited by  $\Lambda_c^*$  and  $\Lambda'$  and for  $\mu > \mu_m$ , it is delimited by  $\Lambda_*$  and  $\Lambda'$ . This region of negative specific heats also defines the physical region of ensembles inequivalence, i.e., the states that are stable in MCE but unstable in CE (metastable states are considered here as stable states). Finally, we have represented the strict region of ensembles inequivalence, i.e., the states that are stable in MCE but unstable or metastable in CE. It is delimited by  $\Lambda_1$  and  $\Lambda_2$  and, of course, contains the negative specific heats region.

The strict caloric curve (see Figs. 39, 43, and 44), corresponding to the fully stable states, is denoted (S). The states (U) are unstable. The states (M) are metastable but they are long lived. We see that there exists a fully stable equilibrium state for any accessible energy and any screening length. This is consistent with the usual Newtonian model in d=1 [20,29].

In conclusion, for  $\mu < \mu_c$ , the system displays canonical and microcanonical second-order phase transitions. For  $\mu_c$  $<\mu < \mu_m$  (canonical tricritical point), the system displays canonical first-order phase transitions and microcanonical second-order phase transitions. For  $\mu > \mu_m$  (microcanonical tricritical point), the system displays canonical and microcanonical first-order phase transitions. Note that the canonical and microcanonical tricritical points do not coincide as also observed in other models [28,38,40,42].

#### 2. Dimensions d=2 and d=3

In Figs. 47 and 48, we plot the series of equilibria in d = 2 and d=3. We have considered different values of  $\mu$  but only the case  $\mu=1$  is shown. We have observed that the shape of the diagrams does not significantly depend on the value of the screening parameter  $\mu$ . Therefore, the description of these diagrams is similar to the one given in Secs. III F 2 and III F 3 for the modified Newtonian model.

## V. STABILITY OF THE HOMOGENEOUS PHASE

In this section, we study the stability of the homogeneous phase in the case where the potential satisfies the modified Poisson equation (44) or the screened Poisson equation (65). We first consider the spectral stability of the homogeneous phase with respect to the Smoluchowski equation or, equivalently, with respect to the Keller-Segel model. This will al-



FIG. 48. Caloric curve in d=3 for  $\mu=1$ .

low us to determine the growth rate (unstable case) or the damping rate (stable case) of the perturbation. Then, we investigate the dynamical and thermodynamical stability of a larger class of systems by determining whether the homogeneous phase is a maximum of entropy at fixed mass and energy in MCE or a minimum of free energy at fixed mass in CE.

#### A. Spectral stability

We consider the mean field Smoluchowski equation

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left[ \frac{1}{\xi} \left( \frac{k_B T}{m} \nabla \rho + \rho \nabla \Phi \right) \right], \tag{89}$$

coupled to the modified Poisson equation (44) or to the screened Poisson equation (65). The boundary conditions are given by Eq. (46). Up to a change of notation, these equations also describe the Keller-Segel model (32)-(38) or (32)-(40). In the modified Newtonian model, the homogeneous steady state satisfies

$$\rho = \overline{\rho}, \quad \Phi = 0. \tag{90}$$

In the screened Newtonian model, it satisfies

$$-k_0^2 \Phi = S_d G \rho, \tag{91}$$

where  $\rho$  and  $\Phi$  are uniform. In both models, the linearized equations can be written as

$$\xi \frac{\partial \delta \rho}{\partial t} = \frac{k_B T}{m} \Delta \delta \rho + \rho \Delta \delta \Phi, \qquad (92)$$

$$\Delta \delta \Phi - k_0^2 \delta \Phi = S_d G \delta \rho, \qquad (93)$$

where  $k_0=0$  in the modified Newtonian model and  $k_0 \neq 0$  in the screened Newtonian model.

In an infinite domain, the spectral stability of the homogeneous solutions of the modified Smoluchowski-Poisson system and Keller-Segel model (and their generalizations) has been studied by Chavanis [70] and Chavanis and Sire [71] who stressed the analogy with the Jeans instability in astrophysics [72]. Interestingly, there is no "(Jeans) swindle" in the stability analysis of the chemotactic problem since an homogeneous distribution *is* a steady state of the KellerSegel model as explained previously. Here, we describe how the results are modified in a bounded domain with the boundary conditions (46). This problem was considered by Keller and Segel [3] in d=2. We shall perform the stability analysis in d dimensions. Let us call  $\psi_k(\mathbf{r})$  the eigenfunctions of the Laplacian and  $-k^2$  the corresponding eigenvalues. They are solution of

$$\Delta \psi_k = -k^2 \psi_k, \tag{94}$$

with

$$\nabla \psi_k \cdot \mathbf{n} = 0 \tag{95}$$

on the boundary. It is easy to check that the eigenvalues are necessarily negative (hence the notation  $-k^2$ ). Indeed, multiplying Eq. (94) by  $\psi_k$ , integrating on the whole domain, and using an integration by parts, we get  $\int (\nabla \psi_k)^2 d\mathbf{r} = k^2 \int \psi_k^2 d\mathbf{r}$ , which proves the result. In a bounded domain, their values are "quantized" (see below). The lowest nonzero value of k will play a particular role as it determines the critical temperature below which the homogeneous phase becomes unstable. The expression of the eigenfunctions and eigenvalues depends on the domain shape and on the dimension of space. In the following, we shall work in a spherical box in d = 1, 2, 3 dimensions.

(i) In d=1, we have

$$\psi_n = \cos(k_n x), \tag{96}$$

with

$$k_n = n \frac{\pi}{R},\tag{97}$$

where *n* is an integer. The smallest nonzero eigenvalue is  $k_1 = \pi/R$ .

(ii) In d=2, we have

$$\psi_{ni} = J_n(k_{ni}r)\cos(n\theta), \qquad (98)$$

with

$$k_{ni} = \frac{\gamma_{ni}}{R},\tag{99}$$

where *n* is an integer and  $\gamma_{ni}$  is the *i*th zero of  $J'_n(x)$ . The smallest nonzero eigenvalue is  $k_{01} = \gamma_{01}/R$  where  $\gamma_{01} = j_{11} = 3.83171\cdots$  is the first zero of  $J'_0(x) = -J_1(x)$ . The axisymmetric mode (n=0) is

$$\psi_{0i} = J_0(k_{0i}r). \tag{100}$$

(iii) In d=3, we have

$$\psi_{lmi} = \frac{1}{\sqrt{r}} J_{l+1/2}(k_{li}r) Y_{lm}(\theta, \phi), \qquad (101)$$

with

$$k_{li} = \frac{\gamma_{li}}{R},\tag{102}$$

where *l*, *m* are integers with  $l \ge |m|$  and  $\gamma_{li}$  is the *i*th zero of

PHASE TRANSITIONS IN SELF-GRAVITATING SYSTEMS...

$$\frac{xJ'_{l+1/2}(x)}{J_{l+1/2}(x)} - \frac{1}{2} = 0.$$
 (103)

The smallest nonzero eigenvalue is  $k_{01} = \gamma_{01}/R$  where  $\gamma_{01} = x_1 = 4.493 \ 41 \cdots$  is the first root of  $\tan(x) = x$ . The spherically symmetric mode (l, m=0) is

$$\psi_{00i} = \frac{\sin(k_{0i}r)}{r}.$$
 (104)

The solutions of the linearized equations (92) and (93) can be expanded on the eigenmodes, writing

$$\delta\rho(\mathbf{r},t) = \sum_{k} A_{k} e^{\sigma_{k} t/\xi} \psi_{k}(\mathbf{r}), \qquad (105)$$

$$\delta \Phi(\mathbf{r},t) = \sum_{k} B_{k} e^{\sigma_{k} t/\xi} \psi_{k}(\mathbf{r}), \qquad (106)$$

where the sum runs on the (quantized) eigenvalues. Substituting Eqs. (105) and (106) in Eqs. (92) and (93), we obtain the algebraic equations

$$\left(\sigma_k + \frac{k_B T}{m} k^2\right) A_k + \rho k^2 B_k = 0, \qquad (107)$$

$$S_d G A_k + (k^2 + k_0^2) B_k = 0. (108)$$

There will be nontrivial solutions only if the determinant of this system of equations is zero. This yields the dispersion relation

$$\sigma_k = \left(\frac{S_d G \rho}{k^2 + k_0^2} - \frac{k_B T}{m}\right) k^2, \qquad (109)$$

relating  $\sigma_k$  to the wave number k. The amplitudes  $A_k$  and  $B_k$  are determined by the initial condition. We see that  $\sigma_k$  is real so that the perturbation either grows or decays exponentially rapidly. The homogeneous phase will be spectrally stable if  $\sigma_k < 0$  for all k and it will be spectrally unstable if there exists one or several modes for which  $\sigma_k > 0$ . We note that the dispersion relation (109) is the same as in an infinite domain [71,72]. However, in a finite domain, the allowed wavenumbers k are quantized while they are continuous in an infinite domain.

According to Eq. (109), the system will be unstable if there exists  $k \neq 0$  such that

$$\frac{S_d G \rho}{k^2 + k_0^2} > \frac{k_B T}{m}.\tag{110}$$

Therefore, a necessary condition of instability is that

$$\frac{k_B T}{m} < \frac{S_d G \rho}{k_f^2 + k_0^2} = \frac{k_B T_c^*}{m},$$
(111)

where  $k_f$  is the smallest nonzero wave number. For  $T > T_c^*$ , the homogeneous distribution is stable for perturbations with arbitrary wave numbers. For  $T < T_c^*$ , the homogeneous distribution is unstable for perturbations with wave numbers

$$k^{2} < \frac{S_{d}Gm\rho}{k_{B}T} - k_{0}^{2} \equiv k_{m}^{2}.$$
 (112)

For  $k_0=0$ , the critical temperature is

$$\frac{k_B T_c^*}{m} = \frac{S_d G \rho}{k_f^2},\tag{113}$$

and we recover the Jeans criterion

$$k^2 < \frac{S_d Gm\rho}{k_B T} \equiv k_J^2. \tag{114}$$

In the general case, the instability criterion can be written as

$$k^2 < k_J^2 - k_0^2 \equiv k_m^2. \tag{115}$$

We see that for the screened Newtonian potential  $(k_0 \neq 0)$ , the instability occurs for larger wavelengths as compared to the Newtonian model  $(k_0=0)$ . Let us introduce the notation

$$k_B T_c = \frac{S_d Gm\rho}{k_0^2},\tag{116}$$

which corresponds to the critical temperature in an infinite domain  $(k_f=0)$ . Since the dispersion relation (109) does not explicitly depend on  $k_f$ , it is convenient to introduce the notation (116). We have

$$T_c^* = \frac{T_c}{1 + (k_f/k_0)^2}.$$
 (117)

For the Newtonian interaction  $(k_0=0)$  and for an infinite domain  $(k_f=0)$ , we have  $T_c^*=+\infty$  so that the system is always unstable to some wavelengths. For  $k_0 \neq 0$  and/or  $k_f \neq 0$ , the instability is suppressed for  $T > T_c^*$ . When  $T < T_c^*$ , the system is unstable for the modes such that

$$k < k_0 \left(\frac{T_c}{T} - 1\right)^{1/2} \equiv k_m(T).$$
 (118)

The growth rate can be written

$$\sigma_k = \frac{k_B T}{m} \frac{k^2 (k_m (T)^2 - k^2)}{k_0^2 + k^2},$$
(119)

where  $k_m(T)$  is given by Eq. (118). It achieves its maximum value for  $k=k_*(T)$  where

$$k_*(T) = k_0 \left[ \left( \frac{T_c}{T} \right)^{1/2} - 1 \right]^{1/2}.$$
 (120)

The corresponding value of the growth rate is

$$\sigma_*(T) = \frac{k_B T_c}{m} k_0^2 \left[ 1 - \left(\frac{T}{T_c}\right)^{1/2} \right]^2.$$
(121)

The number of clusters that is expected to form in the linear regime is  $N(T) = R/[2\pi/k_*(T)]$ . This corresponds to the number of oscillations of the eigenfunction. For a fixed value of  $k_0$ , this number increases as the temperature decreases. The behavior of the different quantities defined above is represented in Figs. 49 and 50.

Let us consider some particular cases.



FIG. 49. Growth ( $\sigma > 0$ ) or decay ( $\sigma < 0$ ) rate as a function of the wavenumber *k*. The system is unstable for  $k < k_m(T)$  and the maximum growth rate is reached for  $k=k_*(T)$ . The parameters have been scaled such that  $k_0=1$ ,  $T_c=1$ , and T=1/2.

(i) For 
$$T=T_c$$
, we have  $k_m=0$ ,  $k_*=0$ ,  $\sigma_*=0$ , and

$$\sigma_k = -\frac{k_B T_c}{m} \frac{k^4}{k_0^2 + k^2} < 0.$$
(122)

Therefore, the system is stable. More generally, for  $T \ge T_c$ , the system is stable. For  $T \rightarrow +\infty$ , we have  $\sigma_k = -\frac{k_B T}{m}k^2$ .

(ii) For T=0, we have  $k_m \to +\infty$ ,  $k_* \to +\infty$ ,  $\sigma_* \to k_B T_c k_0^2/m$  and

$$\sigma_k = \frac{k_B T_c}{m} \frac{k_0^2 k^2}{k_0^2 + k^2}.$$
 (123)

The growth rate is maximum for  $k_* \rightarrow +\infty$ , i.e., for very small wavelengths  $\lambda_* \rightarrow 0$ . In that case, we expect a very large number of clusters in the linear regime.

(iii) For  $k_0=0$  (modified Newtonian model), we have

$$\sigma_k = S_d G \rho - \frac{k_B T}{m} k^2. \tag{124}$$

The system is unstable for  $T < T_c^*$  where the critical temperature is given by Eq. (113). Furthermore, the unstable wave-



FIG. 50. Evolution of  $k_m$ ,  $k_*$ , and  $\sigma_*$  as a function of the temperature. The parameters have been scaled such that  $k_0=1$  and  $T_c = 1$ .



FIG. 51. Growth ( $\sigma$ >0) rate as a function of the wave number k in two limits: (i) the Newtonian limit  $k_0=0$  (and  $T\neq 0$ ) for which the maximum growth rate corresponds to  $k_*=k_f \leq 1$  (large scales), and (ii) the cold limit T=0 (and  $k_0\neq 0$ ) for which the maximum growth rate corresponds to  $k_*\rightarrow+\infty$  (small scales).

numbers correspond to  $k < k_J$  where the Jeans wavenumber is given by Eq. (114). For  $T \neq 0$ , the growth rate is maximum for  $k_*=k_f$ , i.e., for the maximum wavelength  $\lambda_f=2\pi/k_f$ . In that case, we have only one cluster. The corresponding value of the growth rate is  $\sigma_*=S_d G \rho - k_B T k_f^2/m$ . For T=0, we have  $\sigma_k=S_d G \rho$  so that the growth rate is independent on the scale. The two limit cases discussed above are illustrated in Fig. 51.

## B. Thermodynamical stability

We now analyze the thermodynamical stability of the homogeneous phase by using variational principles. Basically, we have to solve the maximization problem (3) in MCE and the minimization problem (18) in CE. However, for spatially homogeneous systems, it is shown in Appendix A that they are both *equivalent* to the minimization problem (25). Therefore, the system is stable iff the second order variations of free energy (28) are positive definite for any perturbations  $\delta\rho$ that conserve mass, i.e.,  $\int \delta\rho d\mathbf{r} = 0$ . We are led therefore to considering the eigenvalue problem

$$\delta \Phi_{\lambda} + \frac{k_B T}{\rho m} \delta \rho_{\lambda} = \lambda \, \delta \rho_{\lambda}, \qquad (125)$$

$$\Delta \delta \Phi_{\lambda} - k_0^2 \delta \Phi_{\lambda} = S_d G \delta \rho_{\lambda}. \tag{126}$$

If all the eigenvalues  $\lambda$  are positive, then the system is stable since  $\delta^2 F = \frac{1}{2} \Sigma_{\lambda} \lambda a_{\lambda}^2 \int (\delta \rho_{\lambda})^2 d\mathbf{r} > 0$  where the perturbation has been decomposed under the form  $\delta \rho = \Sigma_{\lambda} a_{\lambda} \delta \rho_{\lambda}$  and  $\delta \Phi$  $= \Sigma_{\lambda} a_{\lambda} \delta \Phi_{\lambda}$ . If at least one eigenvalue is negative, the system is unstable since  $\delta^2 F = \frac{1}{2} \lambda \int (\delta \rho_{\lambda})^2 d\mathbf{r} < 0$  for that perturbation. It is easy to see that the eigenfunctions are

$$\delta \rho_{\lambda}(\mathbf{r}) = A_k \psi_k(\mathbf{r}), \quad \delta \Phi_{\lambda}(\mathbf{r}) = -\frac{S_d G A_k}{k^2 + k_0^2} \psi_k(\mathbf{r}), \quad (127)$$

and that the corresponding eigenvalues are

$$\lambda(k) = -\frac{S_d G}{k^2 + k_0^2} + \frac{k_B T}{\rho m}$$
(128)

for all quantized k (see Sec. V A). We note that  $\int \psi_k d\mathbf{r} = -\frac{1}{k^2} \int \Delta \psi_k d\mathbf{r} = -\frac{1}{k^2} \oint \nabla \psi_k \cdot d\mathbf{S} = 0$  so that  $\int \delta \rho d\mathbf{r} = 0$  as required. Regrouping all these results, we conclude that the system is stable if and only if

$$\frac{S_d G}{k^2 + k_0^2} - \frac{k_B T}{\rho m} < 0 \tag{129}$$

for all (quantized) k. This returns the stability condition obtained in Sec. V A. Therefore, the system is stable iff  $T > T_c^*$ . If  $T < T_c^*$ , the homogeneous phase is an unstable saddle point of free energy at fixed mass. This method determines the thermodynamical stability (or instability) of the homogeneous phase in the canonical and microcanonical ensembles. This implies the stability (or instability) with respect to the mean-field Kramers equation (22), with respect to the Smoluchowski equation (29), with respect to the Keller-Segel model (32), and with respect to the kinetic equation (14).

We can now determine the values of the normalized inverse temperature  $\eta_c^*$  and normalized energy  $\Lambda_c^*$  above which the homogeneous phase becomes unstable. Using Eqs. (52) and (111), we get

$$\eta_c^* = \frac{1}{d} (k_f^2 + k_0^2) R^2.$$
(130)

We obtain

$$\eta_c^* = \pi^2 + \mu^2 = 9.869\ 604\ 4 + \mu^2 \quad (d=1), \qquad (131)$$

$$\eta_c^* = \frac{1}{2}(j_{11}^2 + \mu^2) = 7.341\ 000\ 8 + \frac{\mu^2}{2} \quad (d=2), \quad (132)$$

$$\eta_c^* = \frac{1}{3}(x_1^2 + \mu^2) = 6.730\ 244\ 5 + \frac{\mu^2}{3} \quad (d=3).$$
 (133)

The corresponding critical energy is given by Eq. (64) for the modified Newtonian model and by Eq. (88) for the screened Newtonian model.

#### VI. CONCLUSION

In this paper, we have completed the description of phase transitions in self-gravitating systems and bacterial populations. We have introduced generalized models in which the ordinary Poisson equation is modified and allows for the existence of a spatially homogeneous phase. This avoids the Jeans swindle [77] and leads to a great variety of microcanonical and canonical phase transitions between homogeneous and inhomogeneous states. These generalized models can have application in chemotaxis where the degradation of the chemical leads to a shielding of the interaction and in cosmology where the expansion of the universe creates a sort of "neutralizing background" (in the comoving frame). In this paper, we have only considered equilibrium states. In future works, we shall study the dynamics of some simple

models for which the present study can be a useful guide.

Our study of the modified Newtonian model also allows us to explore the link between cosmology where one studies the evolution of the universe as a whole [12] and stellar dynamics where one studies the structure of individual galaxies [78]. The description of phase transitions in these two disciplines is usually very different [79]. However, our study allows us to make some basic connections. In cosmology, one usually starts from an infinite homogeneous distribution (in an expanding background) and study the appearance of clusters representing galaxies. Our thermodynamical approach shows that, indeed, the homogeneous phase is unstable for sufficiently low temperatures and energies and leads to clusters. The formation of these clusters can be studied by making a linear stability analysis of the Vlasov or Euler equations [12]. Then, in the nonlinear regime, the system is expected to achieve a statistical equilibrium state due to violent relaxation or collisional relaxation (finite N effects) [78]. This corresponds to the inhomogeneous phase [80]. In d=1, there exists an equilibrium state for any value of energy and temperature. For low energies and temperatures, it is spatially inhomogeneous. In the core of the cluster, the density is so high that we can disregard the effect of the neutralizing background. In that case, the statistical equilibrium state (representing an individual "galaxy") is described by the Camm [81] solution like in one-dimensional stellar dynamics. In d=3, there is no inhomogeneous equilibrium state and, for sufficiently small energies and temperatures, the system undergoes a gravothermal catastrophe or an isothermal collapse. In d=2, the situation is intermediate. There exists an equilibrium state in the microcanonical ensemble for all energies while in the canonical ensemble no equilibrium state exists at low temperatures. Similar behaviors occur in chemotaxis and will be investigated in future papers. Note that for ordinary self-gravitating systems, the proper statistical ensemble is the microcanonical ensemble while in chemotaxis (or for the academic model of self-gravitating Brownian particles) the proper statistical ensemble is the canonical one. It is therefore interesting to study these two systems in parallel to describe the analogies and differences between statistical ensembles.

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## APPENDIX A: EQUIVALENT BUT SIMPLER OPTIMIZATION PROBLEMS

In this Appendix, following and extending the approach of Padmanabhan [22] and Chavanis [27], we shall reduce the optimization problems (3) and (18) to simpler forms. In particular, we shall show that the optimization problems (3) and (18) for  $f(\mathbf{r}, \mathbf{v})$  are equivalent to the optimization problems (A6) and (A25) for  $\rho(\mathbf{r})$ .

#### 1. Microcanonical ensemble

To solve the maximization problem (3) we can proceed in two steps. We first maximize the entropy at fixed energy, mass, *and* density profile  $\rho(\mathbf{r})$ . Since the specification of  $\rho(\mathbf{r})$  determines the mass and the potential energy, this is equivalent to maximizing the entropy at fixed kinetic energy and density profile. Writing

$$\delta S - \frac{1}{T} \delta \left( \int f \frac{v^2}{2} d\mathbf{r} d\mathbf{v} \right) - \int \lambda(\mathbf{r}) \delta \left( \int f d\mathbf{v} \right) d\mathbf{r} = 0,$$
(A1)

this leads to the Maxwellian distribution function

$$f(\mathbf{r}, \mathbf{v}) = \left(\frac{m}{2\pi k_B T}\right)^{d/2} \rho(\mathbf{r}) e^{-mv^2/2k_B T},$$
 (A2)

which is the global entropy maximum with the previous constraints since  $\delta^2 S = -k_B \int \frac{(\delta f)^2}{2fm} d\mathbf{r} d\mathbf{v} < 0$  (the constraints are linear in *f* so that their second variations vanish). Using Eq. (A2), we can now express the entropy and the energy in terms of  $\rho(\mathbf{r})$  and *T*. Up to unimportant constants, we obtain

$$S = \frac{d}{2}Nk_B \ln T - k_B \int \frac{\rho}{m} \ln \frac{\rho}{m} d\mathbf{r}, \qquad (A3)$$

$$E = \frac{d}{2}Nk_BT + \frac{1}{2}\int \rho(\mathbf{r},t)u(\mathbf{r},\mathbf{r}')\rho(\mathbf{r}',t)d\mathbf{r}d\mathbf{r}' + \int \rho V d\mathbf{r}.$$
(A4)

The temperature T can be determined from the energy constraint (A4) and substituted in Eq. (A3). Therefore, the entropy becomes a functional of the density alone given by

$$S = \frac{d}{2}Nk_B \ln(E - W[\rho]) - k_B \int \frac{\rho}{m} \ln \frac{\rho}{m} d\mathbf{r}, \qquad (A5)$$

where  $W[\rho]$  is the potential energy in Eq. (A4), i.e., the sum of the second and third terms. By this way, the energy constraint has explicitly been taken into account in the expression of the entropy.

We now have to solve the maximization problem

$$\max\{S[\rho]|M[\rho] = M\},\tag{A6}$$

where  $S[\rho]$  is given by Eqs. (A3) and (A4) or, equivalently, by Eq. (A5). Finally, the solution of (3) is given by the distribution function (A2) with the density profile that is solution of (A6). Let us compute the variations of entropy and energy up to second order. We have

$$\Delta S = \frac{d}{2}Nk_B\frac{\delta T}{T} - k_B \int \left(\ln\frac{\rho}{m} + 1\right)\frac{\delta\rho}{m}d\mathbf{r} - \frac{d}{4}Nk_B\left(\frac{\delta T}{T}\right)^2 - k_B \int \frac{(\delta\rho)^2}{2\rho m}d\mathbf{r},$$
(A7)

$$\Delta E = \frac{d}{2}Nk_B\delta T + \int \Phi\,\delta\rho d\mathbf{r} + \frac{1}{2}\int\,\delta\rho\,\delta\Phi d\mathbf{r}\,.$$
(A8)

Using the conservation of energy  $\Delta E=0$  to eliminate  $\delta T$  [or working directly on Eq. (A5)], we obtain

$$\Delta S = -\frac{1}{T} \int \Phi \,\delta\rho d\mathbf{r} - k_B \int \left( \ln \frac{\rho}{m} + 1 \right) \frac{\delta\rho}{m} d\mathbf{r}$$
$$-\frac{1}{2T} \int \,\delta\rho \,\delta\Phi d\mathbf{r} - \frac{1}{dNk_B T^2} \left( \int \Phi \,\delta\rho d\mathbf{r} \right)^2$$
$$-k_B \int \frac{(\delta\rho)^2}{2\rho m} d\mathbf{r}. \tag{A9}$$

Let us determine the critical points of (A6) that cancel the first-order variations. At first order, we have

$$\delta S = -\frac{1}{T} \int \Phi \,\delta \rho d\mathbf{r} - k_B \int \left( \ln \frac{\rho}{m} + 1 \right) \frac{\delta \rho}{m} d\mathbf{r}.$$
 (A10)

The conservation of mass can be taken into account by introducing a Lagrange multiplier. Writing the variational principle as

$$\delta S - \alpha \, \delta M = 0, \tag{A11}$$

we obtain the mean field Boltzmann distribution

$$\rho = A' e^{-m\Phi/k_B T},\tag{A12}$$

where  $\Phi(\mathbf{r})$  is given by Eq. (7). Combining Eq. (A12) with Eq. (A2), we recover the mean field Maxwell-Boltzmann distribution (10). However, the present approach allows us to simplify the condition of thermodynamical stability. Indeed, the system is stable in the microcanonical ensemble if and only if the second order variations of entropy (A9) are negative definite

$$-k_B \int \frac{(\delta\rho)^2}{2\rho m} d\mathbf{r} - \frac{1}{2T} \int \delta\rho \,\delta\Phi d\mathbf{r} - \frac{1}{dNk_B T^2} \left(\int \Phi \,\delta\rho d\mathbf{r}\right)^2 \le 0$$
(A13)

for all perturbations  $\delta \rho$  that conserve mass at first order, i.e.,  $\int \delta \rho d\mathbf{r} = 0$  (the conservation of energy has automatically been taken into account in the previous derivation). This stability criterion is equivalent to the stability criterion (13) but it is simpler because it is expressed in terms of the density instead of the distribution function.

In fact, the previous derivation proves the equivalence between (3) and (A6) for global maximization. We shall now go one step further and prove the equivalence between (3) and (A6) for local maximization, i.e.,  $f(\mathbf{r}, \mathbf{v})$  is a (local) maximum of S[f] at fixed energy and mass if and only if the corresponding  $\rho(\mathbf{r})$  is a (local) maximum of  $S[\rho]$  at fixed mass. To that purpose, we shall prove that the stability criteria (13) and (A13) are equivalent. This extension is important because local entropy maxima (metastable states) are fully relevant in the case of systems with long-range interactions [63].

According to Eq. (13), a critical point of entropy at fixed mass and energy is a local maximum if and only if

PHASE TRANSITIONS IN SELF-GRAVITATING SYSTEMS...

$$I[\delta f] \equiv -\int \frac{(\delta f)^2}{2mf} d\mathbf{r} d\mathbf{v} - \frac{1}{2k_B T} \int \delta \rho \,\delta \Phi d\mathbf{r} \leqslant 0$$
(A14)

for all perturbations  $\delta f$  that satisfy  $\delta M = \int \delta f d\mathbf{r} d\mathbf{v} = 0$  and  $\delta E = \int \delta f(\frac{v^2}{2} + \Phi) d\mathbf{r} d\mathbf{v} = 0$ . Let us first determine the distribution function  $\delta f_*(\mathbf{r}, \mathbf{v})$  that maximizes  $I[\delta f]$  with the previous constraints and the additional constraint  $\delta \rho = \int \delta f d\mathbf{v}$ , where  $\delta \rho(\mathbf{r})$  is given (it is only ascribed to conserve mass, i.e.,  $\int \delta \rho d\mathbf{r} = 0$ ). Since the specification of  $\delta \rho$  determines  $\delta \Phi$ , this is equivalent to maximizing  $\tilde{I} = -\int \frac{(\delta f)^2}{2mf} d\mathbf{r} d\mathbf{v}$  with the constraints  $\int \delta f d\mathbf{v} = \delta \rho$ , and  $\frac{1}{2} \int \delta f v^2 d\mathbf{r} d\mathbf{v} = -\int \delta \rho \Phi d\mathbf{r}$ . Introducing Lagrange multipliers, we write the variational problem as

$$\delta \tilde{I} - \int \lambda(\mathbf{r}) \,\delta\!\!\left(\int \,\delta f d\mathbf{v}\right) d\mathbf{r} - \mu \,\delta\!\!\left(\int \,\delta f \frac{v^2}{2} d\mathbf{r} d\mathbf{v}\right) = 0.$$
(A15)

The solution is

$$\delta f_*(\mathbf{r}, \mathbf{v}) = -mf(\mathbf{r}, \mathbf{v}) \left(\mu \frac{v^2}{2} + \lambda(\mathbf{r})\right),$$
 (A16)

and it is clearly the global maximum of  $\tilde{I}$  under the previous constraints since  $\delta^2 \tilde{I} = -\int \frac{(\delta(\delta f))^2}{2mf} d\mathbf{r} d\mathbf{v} \leq 0$  (the constraints are linear in  $\delta f$  so that their second variations vanish). The Lagrange multipliers  $\lambda(\mathbf{r})$  and  $\mu$  are determined by substituting Eq. (A16) in the constraints  $\int \delta f d\mathbf{v} = \delta \rho$ , and  $\frac{1}{2} \int \delta f v^2 d\mathbf{r} d\mathbf{v} = -\int \delta \rho \Phi d\mathbf{r}$ . Noting that a critical point of entropy at fixed mass and energy can be written as in Eq. (12), we have the identities

$$\int f \frac{v^2}{2} d\mathbf{v} = \frac{d}{2} \frac{\rho(\mathbf{r})}{m} k_B T, \qquad (A17)$$

$$\int f \frac{v^4}{4} d\mathbf{v} = \frac{d}{2} \left( 1 + \frac{d}{2} \right) \frac{\rho(\mathbf{r})}{m^2} (k_B T)^2.$$
(A18)

Using these identities, we find after simple calculations that

$$\lambda(\mathbf{r}) = -\frac{\delta\rho}{m\rho} - \frac{d}{2}\mu \frac{k_B T}{m},\tag{A19}$$

$$\mu = \frac{2}{d} \frac{1}{N(k_B T)^2} \int \delta \rho \Phi d\mathbf{r}, \qquad (A20)$$

where we have used the constraint  $\int \delta \rho d\mathbf{r} = 0$  to simplify some terms. Therefore, the optimal perturbation is given by Eq. (A16) with Eqs. (A19) and (A20). Since this perturbation maximizes  $I[\delta f]$  with the above-mentioned constraints, we have  $I[\delta f] \leq I[\delta f_*]$ . Explicating  $I[\delta f_*]$  using Eqs. (A14), (A16), (A19), and (A20), we obtain after simple calculations

$$I[\delta f] \leq -\int \frac{(\delta \rho)^2}{2m\rho} d\mathbf{r} - \frac{1}{2k_B T} \int \delta \rho \, \delta \Phi d\mathbf{r} - \frac{1}{dN(k_B T)^2} \left(\int \delta \rho \Phi d\mathbf{r}\right)^2 \equiv I[\delta \rho], \quad (A21)$$

where the right-hand side is precisely the functional appear-

ing in Eq. (A13). Furthermore, there is equality in Eq. (A21) if and only if  $\delta f = \delta f_*$ . This proves that the stability criteria (13) and (A13) are equivalent. Indeed, (i) if inequality (A13) is fulfilled for all perturbations  $\delta \rho$  that conserve mass, then according to Eq. (A21), we know that inequality (13) is fulfilled for all perturbations  $\delta f$  that conserve mass and energy at first order; (ii) if there exists a perturbation  $\delta \rho_c$  that makes  $I[\delta \rho] > 0$ , then the perturbation  $\delta f_c$  given by Eq. (A16) with Eqs. (A19) and (A20) and  $\delta \rho = \delta \rho_c$  makes  $I[\delta f] > 0$ . In conclusion, the stability criteria (13) and (A13) are equivalent.

## 2. Canonical ensemble

To solve the maximization problem (18) we can proceed in two steps. We first minimize the free energy at fixed mass and density profile  $\rho(\mathbf{r})$ . This is equivalent to minimizing the free energy at fixed density profile. Writing

$$\delta F + T \int \lambda(\mathbf{r}) \,\delta\!\!\left(\int f d\mathbf{v}\right) d\mathbf{r} = 0, \qquad (A22)$$

this leads to the Maxwellian distribution function

$$f(\mathbf{r}, \mathbf{v}) = \left(\frac{m}{2\pi k_B T}\right)^{d/2} \rho(\mathbf{r}) e^{-mv^2/2k_B T},$$
 (A23)

which is the global minimum of free energy with the previous constraint since  $\delta^2 F = k_B T \int \frac{(\delta f)^2}{2fm} d\mathbf{r} d\mathbf{v} > 0$  (the constraint is linear in *f* so that its second variations vanish). Using Eq. (A23), we can now express the free energy in terms of  $\rho(\mathbf{r})$ . Up to unimportant constants, we get

$$F = \frac{1}{2} \int \rho(\mathbf{r}, t) u(\mathbf{r}, \mathbf{r}') \rho(\mathbf{r}', t) d\mathbf{r} d\mathbf{r}' + \int \rho V d\mathbf{r} + k_B T \int \frac{\rho}{m} \ln \frac{\rho}{m} d\mathbf{r}.$$
 (A24)

We now have to solve the minimization problem

$$\min_{\rho} \{ F[\rho] | M[\rho] = M \}.$$
(A25)

Finally, the solution of (18) is given by the distribution function (A23) with the density profile that is solution of Eq. (A25). The first variations,

$$\delta F + \alpha T \delta M = 0, \qquad (A26)$$

lead to the mean-field Boltzmann distribution

$$\rho = A' e^{-m\Phi/k_B T},\tag{A27}$$

where  $\Phi(\mathbf{r})$  is given by Eq. (7). Combining Eq. (A27) with Eq. (A23), we recover the mean-field Maxwell-Boltzmann distribution (10). However, the present approach allows us to simplify the condition of thermodynamical stability. Indeed, the system is stable in the canonical ensemble iff the second order variations of free energy (A24) are positive definite

$$\frac{1}{2}\int \delta\rho \delta\Phi d\mathbf{r} + \frac{k_B T}{m}\int \frac{(\delta\rho)^2}{2\rho} d\mathbf{r} \ge 0 \qquad (A28)$$

for all perturbations  $\delta \rho$  that conserve mass at first order, i.e.,  $\int \delta \rho d\mathbf{r} = 0$ . This stability criterion is equivalent to the stability

criterion (21) but it is simpler because it is expressed in terms of the density instead of the distribution function.

In fact, the previous derivation proves the equivalence between (18) and (A25) for global minimization. We can also prove their equivalence for local minimization, i.e.,  $f(\mathbf{r}, \mathbf{v})$  is a (local) minimum of F[f] at fixed mass if and only if the corresponding  $\rho(\mathbf{r})$  is a (local) minimum of  $F[\rho]$  at fixed mass. To that purpose, we have to prove that the stability criteria (21) and (A28) are equivalent. The method is similar to the one described in the previous section, the only difference being that we have to relax the energy constraint. This amounts to taking  $\mu=0$  in the previous derivation. Therefore, the optimal perturbation that minimizes  $\delta^2 F[\delta f]$ given by Eq. (21) with the constraints  $\int \delta f d\mathbf{v} = \delta \rho$  and  $\int \delta \rho d\mathbf{r} = 0$  is given by Eq. (A16) with Eq. (A19) and  $\mu = 0$ . Since this perturbation minimizes  $\delta^2 F[\delta f]$  with the abovementioned constraints, we have  $\delta^2 F[\delta f] \ge \delta^2 F[\delta f_*]$ . Explicating  $\delta^2 F[\delta f_*]$  using Eqs. (21), (A16), and (A19), and  $\mu$ =0, we obtain after simple calculations

$$\delta^2 F[\delta f] \ge \frac{1}{2} \int \delta \rho \,\delta \Phi \, d\mathbf{r} + \frac{k_B T}{m} \int \frac{(\delta \rho)^2}{2\rho} d\mathbf{r} \equiv \delta^2 F[\delta \rho],$$
(A29)

where the right-hand side is precisely the functional appearing in Eq. (A28). This proves the equivalence between (21) and (A28) (the argument is the same as in the previous section except that  $\delta f$  is not ascribed to conserve energy anymore).

*Remark.* From the stability criteria (A13) and (A28), we clearly see that canonical stability implies microcanonical stability (but not the converse). Indeed, since the last term in Eq. (A13) is negative, it is clear that if inequality (A28) is satisfied, then inequality (A13) is automatically satisfied. In general, this is not reciprocal and we may have ensembles inequivalence. However, if we consider a spatially homogeneous system for which  $\Phi$  is uniform, the last term in Eq. (A13) vanishes (since the mass is conserved) and the stability criteria (A13) and (A28) coincide. Therefore, for spatially homogeneous systems, we have ensembles equivalence.

# APPENDIX B: EXPLICIT EXPRESSIONS OF THE POTENTIAL

In this Appendix, we limit ourselves to the case d=1 although the results can be easily generalized to any dimension. Using standard methods, we can obtain the Green function associated with the screened Poisson equation (65) in a box with Neumann boundary conditions. Then, we find that the potential is explicitly given by

$$\Phi(x) = \int_{-R}^{R} \rho(x') u(x, x') dx',$$
 (B1)

with

$$u(x,x') = -\frac{G}{k_0} \frac{1}{\sinh(2k_0 R)} (\cosh[k_0(2R - |x - x'|)] + \cosh[k_0(x + x')]).$$
(B2)

In an infinite domain  $(R \rightarrow +\infty)$ , we obtain

$$u(|x - x'|) = -\frac{G}{k_0} e^{-k_0|x - x'|}.$$
(B3)

Similarly, for the modified Newtonian model (44) with Neumann boundary conditions, the potential is explicitly given by

$$\Phi(x) = G \int_{-R}^{R} (\rho - \overline{\rho})(x') |x - x'| dx', \qquad (B4)$$

and this expression remains valid in an infinite domain  $(R \rightarrow +\infty)$ .

## APPENDIX C: EXTERNAL POTENTIAL FOR THE MODIFIED NEWTONIAN MODEL

For the modified Newtonian model (44), the potential can be written as

$$\Phi(\mathbf{r}) = \int (\rho - \overline{\rho})(\mathbf{r}')u(\mathbf{r}, \mathbf{r}')d\mathbf{r}', \qquad (C1)$$

where  $u(\mathbf{r}, \mathbf{r}')$  is the Green function of the Poisson equation with Neumann boundary conditions. Comparing Eq. (C1) with Eq. (7), we find that the external potential is

$$V(\mathbf{r}) = -\bar{\rho} \int u(\mathbf{r}, \mathbf{r}') d\mathbf{r}'.$$
 (C2)

Using Eq. (C2), the potential energy (8) can be written as

$$W = \frac{1}{2} \int \rho \Phi d\mathbf{r} - \frac{1}{2} \overline{\rho} \int \rho(\mathbf{r}) u(\mathbf{r}, \mathbf{r}') d\mathbf{r} d\mathbf{r}'.$$
(C3)

Interchanging the dummy variables  $\mathbf{r}$  and  $\mathbf{r'}$  and using the symmetry  $u(\mathbf{r'}, \mathbf{r}) = u(\mathbf{r}, \mathbf{r'})$ , we get

$$W = \frac{1}{2} \int \rho \Phi d\mathbf{r} - \frac{1}{2} \overline{\rho} \int \rho(\mathbf{r}') u(\mathbf{r}, \mathbf{r}') d\mathbf{r} d\mathbf{r}'.$$
(C4)

Finally, using Eq. (7), we obtain

$$W = \frac{1}{2} \int (\rho - \overline{\rho}) \Phi d\mathbf{r} + \frac{1}{2} \overline{\rho} \int V(\mathbf{r}) d\mathbf{r}.$$
 (C5)

Therefore, the potential energy is given by Eq. (54) up to an unimportant additive constant  $\frac{1}{2}\bar{\rho}\int V(\mathbf{r})d\mathbf{r} = -\frac{1}{2}\bar{\rho}^{2}\int u(\mathbf{r},\mathbf{r}')d\mathbf{r}d\mathbf{r}'$ .

In d=1, according to Eq. (B4), the potential of interaction is u=G|x-x'|. Therefore, the external potential (C2) is explicitly given by

$$V(x) = -\bar{\rho}G(x^2 + R^2).$$
 (C6)

The additive constant in the energy (C5) is therefore

$$\frac{1}{2}\bar{\rho}\int_{-R}^{R}V(x)dx = -\frac{4}{3}G\bar{\rho}^{2}R^{3}.$$
 (C7)

## APPENDIX D: THE MINIMUM ENERGY

Let us consider the modified Newtonian model (44) in d = 1. At T=0, the density profile is a Dirac peak  $\rho = M \delta(x)$  and the energy (57) is

$$E = -\frac{1}{4G} \int_{-R}^{R} \left(\frac{d\Phi}{dx}\right)^2 dx.$$
 (D1)

For a symmetric density profile, the modified Poisson equation can be integrated into

$$\Phi'(x) = 2G \int_0^x \rho(x') dx' - 2G\bar{\rho}x,$$
 (D2)

which is the appropriate Gauss theorem. If all the mass is concentrated at x=0, we obtain

$$\Phi'(x) = GM\left(\operatorname{sign}(x) - \frac{x}{R}\right).$$
 (D3)

Substituting this expression in Eq. (D1), we obtain  $E = -GM^2R/6$ . The total normalized energy is therefore

$$\Lambda_{max}^{(1)} = \frac{1}{6}.\tag{D4}$$

This corresponds to the minimum energy of the branch n = 1.

Let us consider the screened Newtonian model (65) in d = 1. At T=0, the density profile is a Dirac peak  $\rho = M\delta(x)$  and the energy (75) is  $E = \frac{1}{2}M\Phi_0$ . According to Eq. (B2), the potential created in x by a mass M located at x'=0 is

$$\Phi(x) = -\frac{GM}{k_0} \frac{\cosh[k_0(R - |x|)]}{\sinh(k_0 R)},$$
 (D5)

where we have used elementary trigonometric identities to simplify the expression. This leads to  $\Phi_0 = -GM/(k_0 \tanh(k_0 R))$  and  $E = -GM^2/(2k_0 \tanh(k_0 R))$ . The total normalized energy is therefore

$$\Lambda_{max}^{(1)} = \frac{1}{2\mu \tanh(\mu)}.$$
 (D6)

This corresponds to the minimum energy of the branch n = 1.

# APPENDIX E: APPROXIMATE EXPRESSIONS OF THE DENSITY PROFILE

In d=1, the screened Emden equation (69) can be written as

$$\frac{d^2\psi}{d\xi^2} = e^{-\psi} - \lambda + \kappa^2 \psi = -\frac{dV}{d\psi},$$
(E1)

with

$$W(\psi) = e^{-\psi} + \lambda \psi - \frac{1}{2}\kappa^2 \psi^2.$$
 (E2)

This is similar to the equation of motion of a particle of unit mass in a potential  $V(\psi)$  where  $\psi$  plays the role of position

and  $\xi$  the role of time. Using the boundary condition  $\psi = \psi'$ =0 at  $\xi$ =0, we find that the first integral (pseudo energy) is

$$\mathcal{E} = \frac{1}{2} \left( \frac{d\psi}{d\xi} \right)^2 + V(\psi) = 1.$$
 (E3)

This first-order differential equation can be easily integrated until  $\xi = \alpha$ , which formally solves the problem.

Let us consider the limit  $\rho_0 \rightarrow +\infty$  corresponding to  $\alpha \rightarrow +\infty$ . In the inner region, the term  $e^{-\psi}$  dominates and Eq. (E1) reduces to the ordinary Emden equation whose solution is the Camm profile [29,81],

$$e^{-\psi} = \frac{1}{\cosh^2(\xi/\sqrt{2})}.$$
 (E4)

In the outer region, the term  $e^{-\psi}$  can be neglected and Eqs. (E1) and (E3) reduce to

$$\frac{d^2\psi}{d\xi^2} = -\lambda + \kappa^2 \psi, \tag{E5}$$

$$\frac{1}{2} \left( \frac{d\psi}{d\xi} \right)^2 + \lambda \psi - \frac{1}{2} \kappa^2 \psi^2 = 1.$$
 (E6)

The boundary condition at the wall is  $\psi'(\alpha) = 0$ . Substituting this result in Eq. (E6), we get  $\lambda \psi(\alpha) - \frac{1}{2}\kappa^2 \psi(\alpha)^2 = 1$ . The physical solution of this equation is  $\psi(\alpha) = (\lambda - \sqrt{\lambda^2 - 2\kappa^2})/\kappa^2$ . Solving Eq. (E5) with these boundary conditions, we find that

$$\psi(\xi) = \frac{\lambda}{\kappa^2} - \frac{1}{\kappa^2} \sqrt{\lambda^2 - 2\kappa^2} \cosh[\kappa(\xi - \alpha)]. \quad (E7)$$

The matching of the outer solution with the inner solution implies that  $\psi_{outer}(0)=0$ . Using  $\kappa \alpha = \mu$ , we obtain

$$\lambda \sim \frac{\sqrt{2\mu}}{\tanh(\mu)} \frac{1}{\alpha}, \quad (\alpha \to +\infty).$$
 (E8)

Finally, substituting the inner profile (E4) in Eq. (74), we obtain at leading order

$$\eta \sim \sqrt{2}\alpha \quad (\alpha \to +\infty).$$
 (E9)

For  $\alpha \to +\infty$ , the density profile tends to a Dirac peak  $\rho = M \delta(x)$ . The potential energy reduces to  $W = \frac{1}{2}M\Phi_0$ . Using Eqs. (80) and (E8), and  $\kappa = \mu/\alpha$ , we recover Eq. (D6).

The modified Emden equation (48) can be studied similarly. In fact, most of the preceding results remain valid by taking  $\kappa=0$ . The potential is  $V(\psi)=e^{-\psi}+\lambda\psi$ . It has a minimum at  $\psi_0=-\ln\lambda$  so that the solution  $\psi(\xi)$  of the Emden equation (with energy  $\mathcal{E}=1$ ) oscillates around this value. Integrating Eq. (E3), the density profiles of the solutions of the branch n=1 are given by

$$\xi = \int_{0}^{\psi} \frac{dx}{\sqrt{2(1 - e^{-x} - \lambda x)}},$$
 (E10)

with  $\xi \leq \alpha$ . The half-period of the oscillations of the function  $\psi(\xi)$  is

$$\frac{L}{2} = \int_{0}^{\psi(\alpha)} \frac{dx}{\sqrt{2(1 - e^{-x} - \lambda x)}},$$
 (E11)

where  $\psi(\alpha)$  is solution of  $e^{-\psi(\alpha)} + \lambda \psi(\alpha) = 1$  obtained from Eq. (E3) with  $\psi'(\alpha) = 0$ . Let us now consider the limit  $\rho_0 \rightarrow +\infty$ . The inner solution is given by the Camm profile (E4) and the outer solution is

$$\psi(\xi) = \frac{1}{\lambda} - \frac{1}{2}\lambda(\xi - \alpha)^2, \qquad (E12)$$

which is consistent with Eq. (E7) when  $\kappa \rightarrow 0$ . The matching condition  $\psi_{outer}(0)=0$  then yields

$$\lambda \sim \frac{\sqrt{2}}{\alpha} \quad (\alpha \to +\infty).$$
 (E13)

Using Eq. (53), we obtain at leading order

$$\eta \sim \sqrt{2\alpha} \quad (\alpha \to +\infty).$$
 (E14)

## **APPENDIX F: THE BIFURCATION POINT**

In this Appendix, we shall determine the point at which the spatially homogeneous branch bifurcates to the spatially inhomogeneous branch and show that it coincides with the point at which the spatially homogeneous branch becomes unstable (see Sec. V). For a more detailed theory of bifurcations, we refer to the paper of Schaff [82].

For the modified Newtonian model, the differential equation determining the field  $\Phi(\mathbf{r})$  at statistical equilibrium can be written as

$$\Delta \Phi = S_d G (A e^{-\beta m \Phi} - \bar{\rho}). \tag{F1}$$

The homogeneous solution corresponds to  $\rho = \bar{\rho}$ ,  $\Phi = 0$ , and  $A = \rho$ . Considering a small perturbation  $\Phi = 0 + \phi(\mathbf{r})$  with  $\phi$ 

 $\ll 1$  around the homogeneous solution and linearizing the differential equation (F1), we obtain

$$\Delta \phi + S_d G \beta m \rho \phi = 0, \tag{F2}$$

with the boundary conditions  $\nabla \phi \cdot \mathbf{n} = 0$  on the boundary. The boundary conditions determine the allowable wavenumbers  $k^2 \equiv S_d G \beta m \rho$ . They take discrete values  $k = k_n$  (see Sec. V) which in turn determine discrete values of the temperature  $T_n$ . The first point of bifurcation corresponds to the smallest wavenumber  $k_f$ . This is associated with the critical temperature (113) at which the homogeneous branch becomes unstable. Other branches of bifurcations appear at smaller temperatures. They correspond to successive quantized values  $k_n$  of the wave number.

For the screened Newtonian model, the differential equation determining the field  $\Phi(\mathbf{r})$  at statistical equilibrium can be written as

$$\Delta \Phi - k_0^2 \Phi = S_d G A e^{-\beta m \Phi}.$$
 (F3)

The homogeneous solution corresponds to  $\rho = \text{const}$ ,  $\Phi = \text{const}$  with  $-k_0^2 \Phi = S_d G \rho$ . Considering a small perturbation  $\Phi = \text{const} + \phi(\mathbf{r})$  with  $\phi \ll 1$  around the homogeneous solution and linearizing the differential equation (F3), we obtain

$$\Delta\phi + (S_d G\beta m\rho - k_0^2)\phi = 0, \qquad (F4)$$

with the boundary conditions  $\nabla \phi \cdot \mathbf{n} = 0$  on the boundary. The boundary conditions determine the allowable wavenumbers  $k^2 \equiv S_d G \beta m \rho - k_0^2$ . The first point of bifurcation corresponds to the smallest wave number  $k_f$  (see Sec. V). This is associated with the critical temperature (111) at which the homogeneous branch becomes unstable. Other branches of bifurcations appear at smaller temperatures. They correspond to the successive quantized values  $k_n$  of the wave number.

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PHASE TRANSITIONS IN SELF-GRAVITATING SYSTEMS...

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ematically well defined. These authors also consider a screened Newtonian interaction. In their studies, the screening is introduced as a procedure of regularization of the basic gravitational force and they are ultimately interested in the small screening limit  $k_0 \rightarrow 0$ . In our study, partly motivated by biological problems (Keller-Segel model), we allow for an arbitrary screening, as it is related to the degradation of the chemical (in the biological problem). We also consider the modified and screened Poisson equations in infinite [70,71] and finite domains (with Neumann boundary conditions in the biological problem), while in the gravitational studies of Joyce *et al.* [73,74], these equations make sense only in infinite domains (and for  $k_0 \rightarrow 0$ ).

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